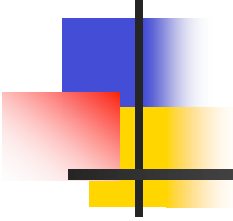


Statistical physics of information processing in biological systems



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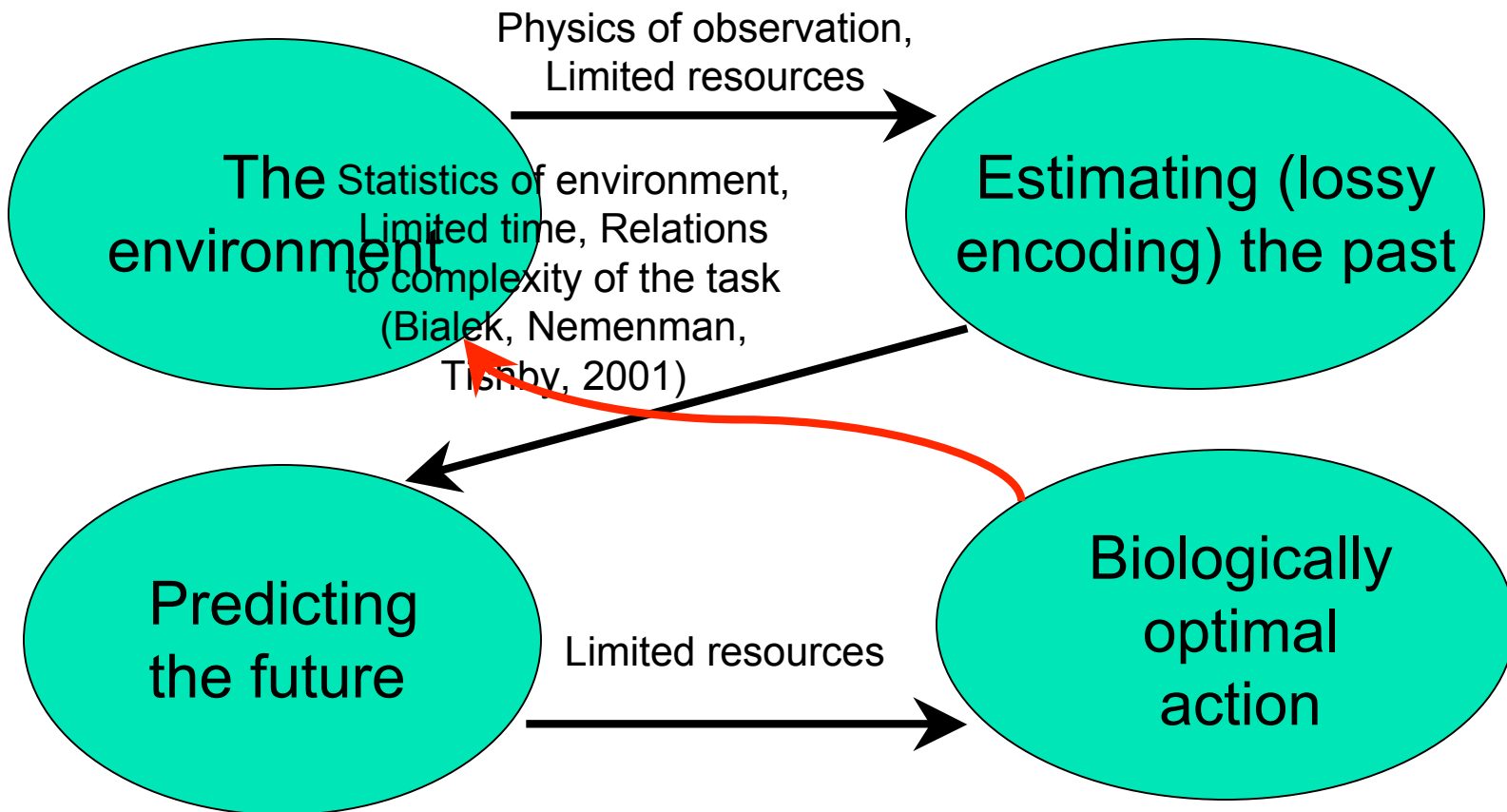


What is theoretical biophysics?

- Risk of answering just (soft, hard condensed matter) physics questions about biological materials/systems.
- Will then know how things happen, not why they happen.
- To be sure: ask questions relevant to behavior.



Life is...



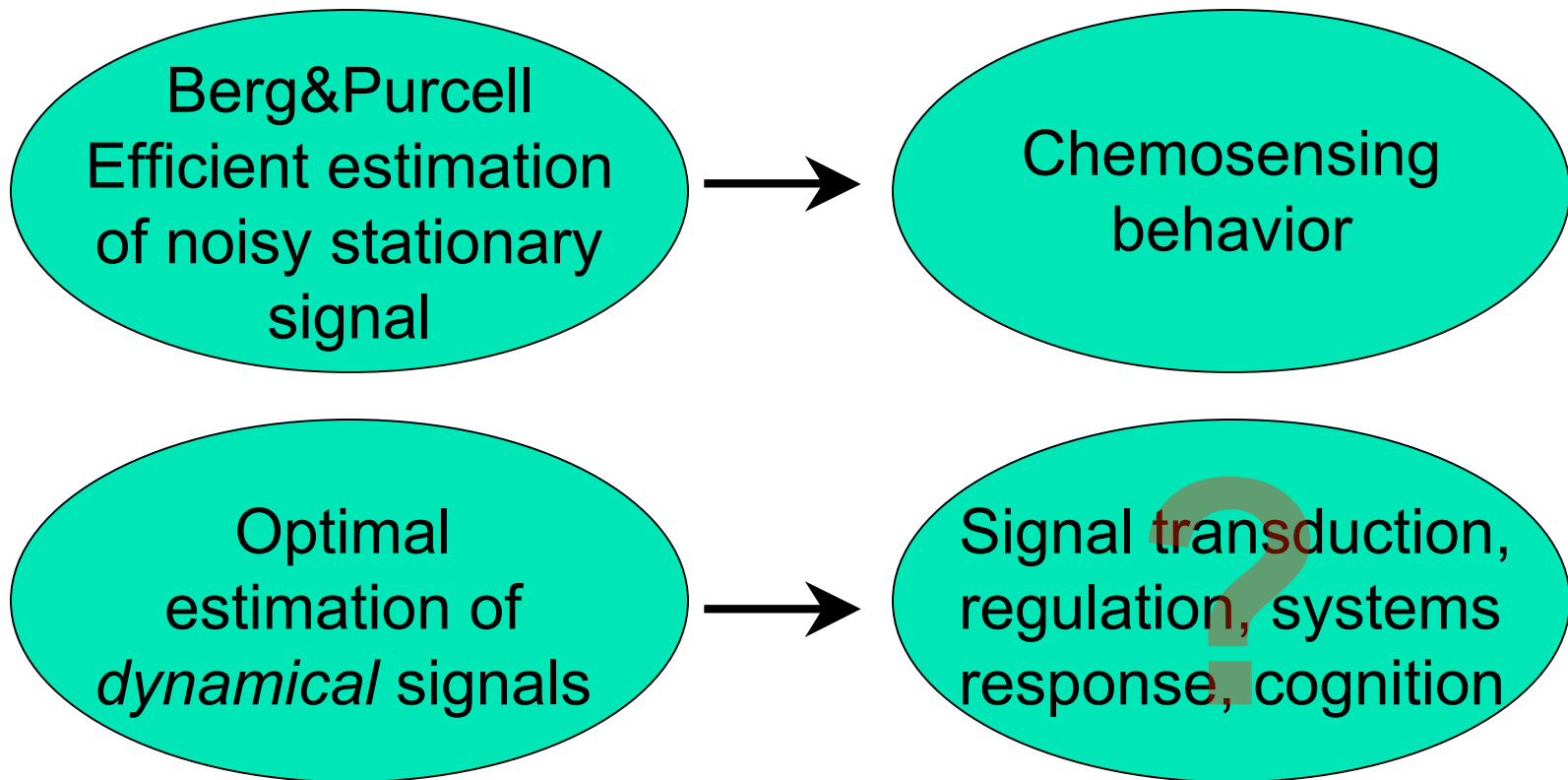


Efficient estimation as a biological design principle

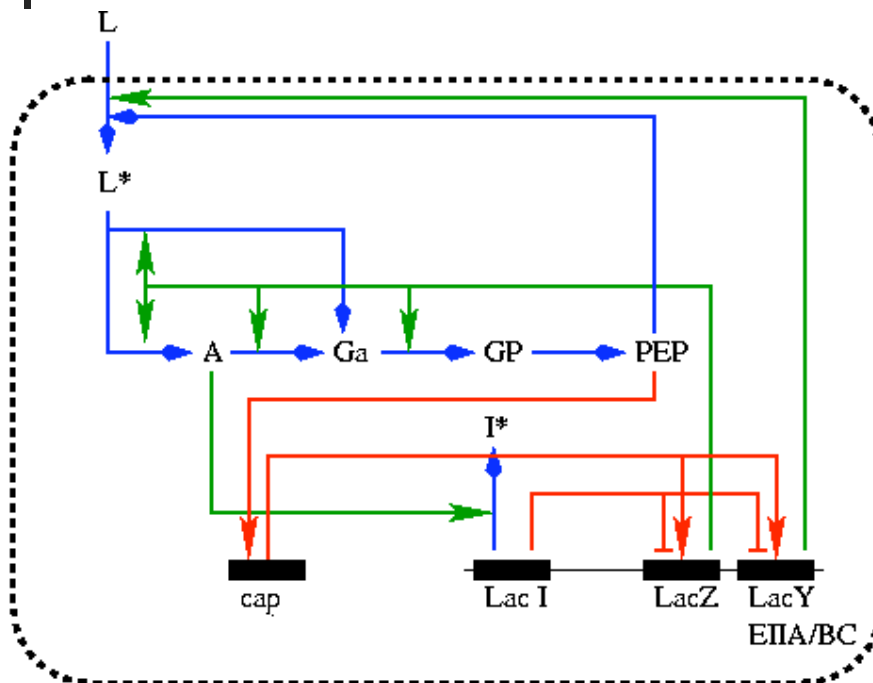
- Berg and Purcell (1977). Chemosensing precision and reliability is limited by physical noise sources
- Since then: single photon responses, transcription, chemotaxis run length, motion estimation in insects, chemotaxis network design - all are at physical limits to sensing.
- Many behaviors and designs need consideration of the remaining arrows (estimation of and reaction to a dynamical stimulus).



Fast learning and active response?



Lac operon and phosphotransferase system



PEP - phosphoenolpyruvate

- Slow positive feedback (lac), 10min
- Very slow positive feedback (cap), 1hr
- Fast negative PEP feedback, 100ms
- Medium-fast positive feedback (PEP), 10s
- Very fast low pass filter (receptor), 10ms

Why?



Statistics of environment

- In a newborn baby (because of the milk-enriched diet) and a non-European adult (because of a certain mutation), lactose enters lower small intestines every few hours - cap averaging sets the mean operating point.
- Bursts appear with time scales of minutes and disappear in tens of minutes - PEP activation, and lac shut-off.
- Chemotaxis leads to higher concentrations on scales of seconds - PEP feedback.



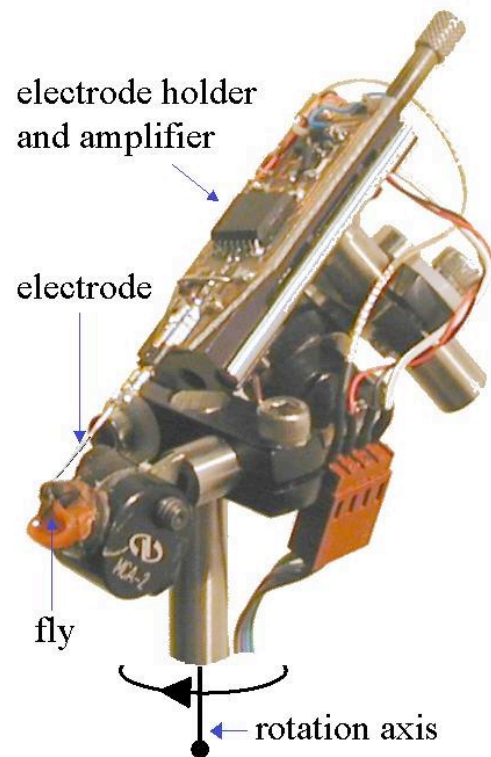
Statistics of environment

- Negative PEP feedback at PEP saturation stabilizes energy production
- Low path filtering at receptors removes statistical noise.

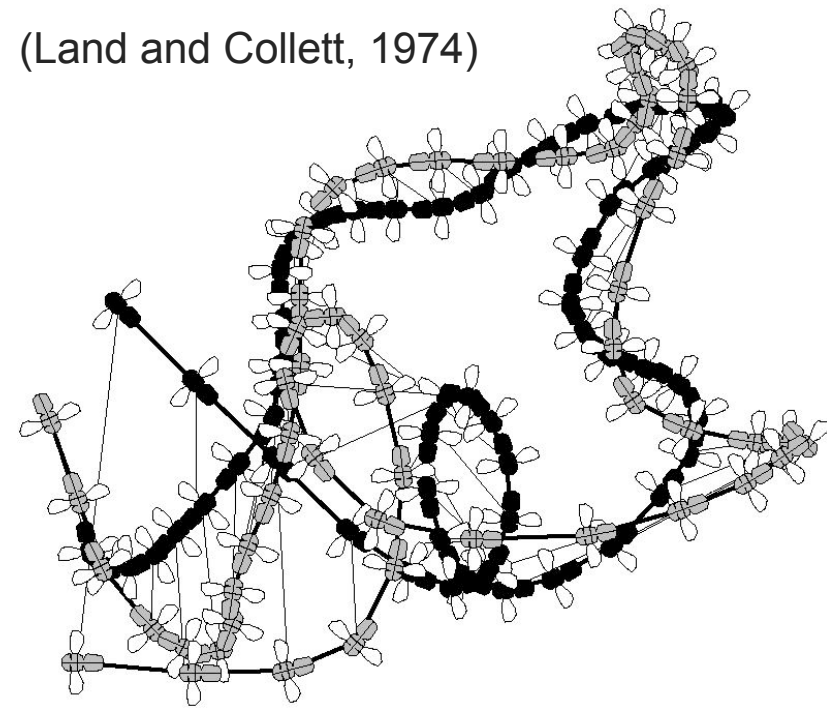
Maybe (near) optimal for this environment?

(with Wall, Bettencourt, Hlavacek)

Motion estimation in fly H1



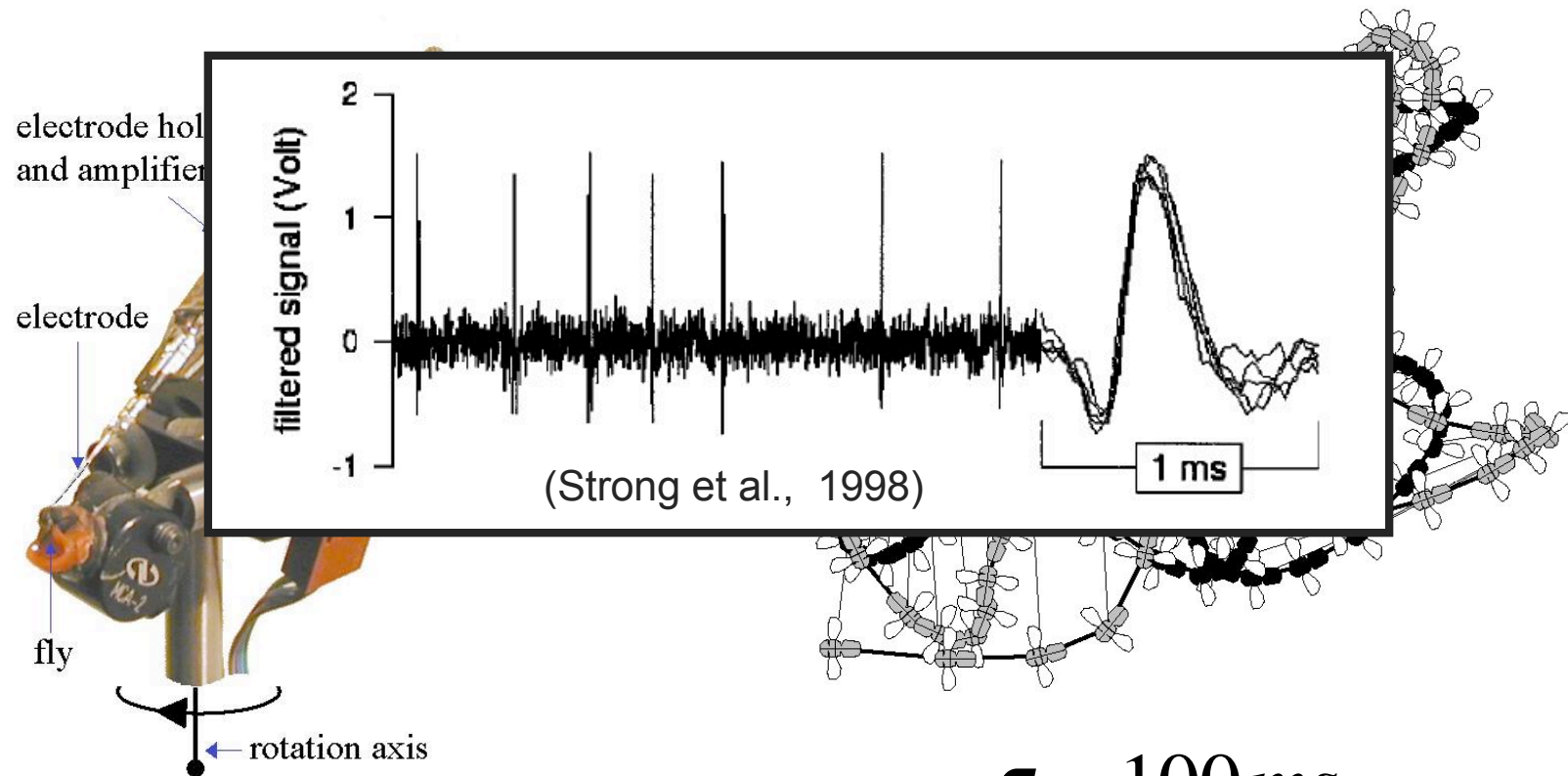
(Lewen et al, 2001)



$$\tau = 100ms$$

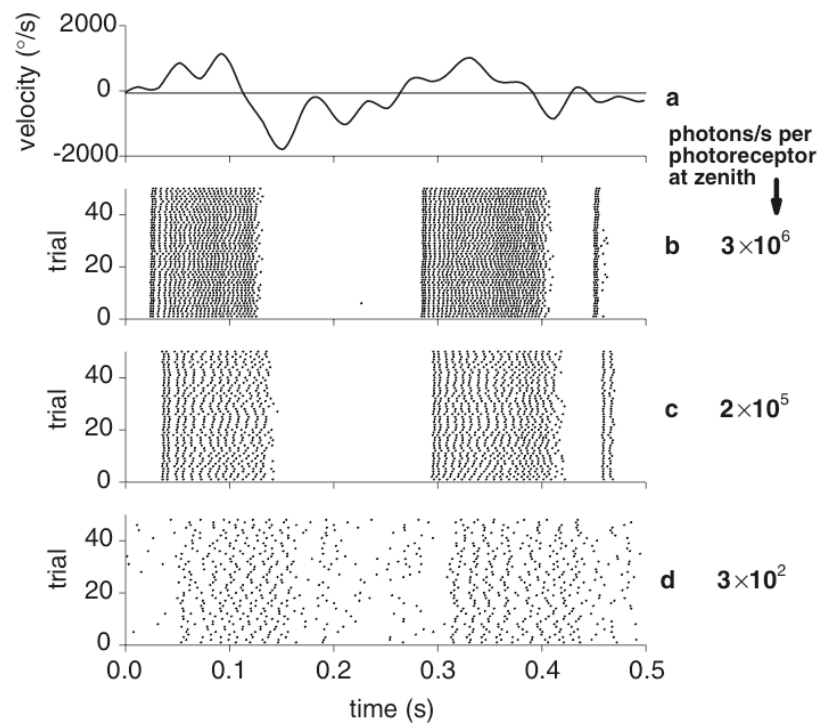
Diffusion in a quadratic potential

Motion estimation in fly H1



$$\tau = 100ms$$

Precision is limited by physical noise sources



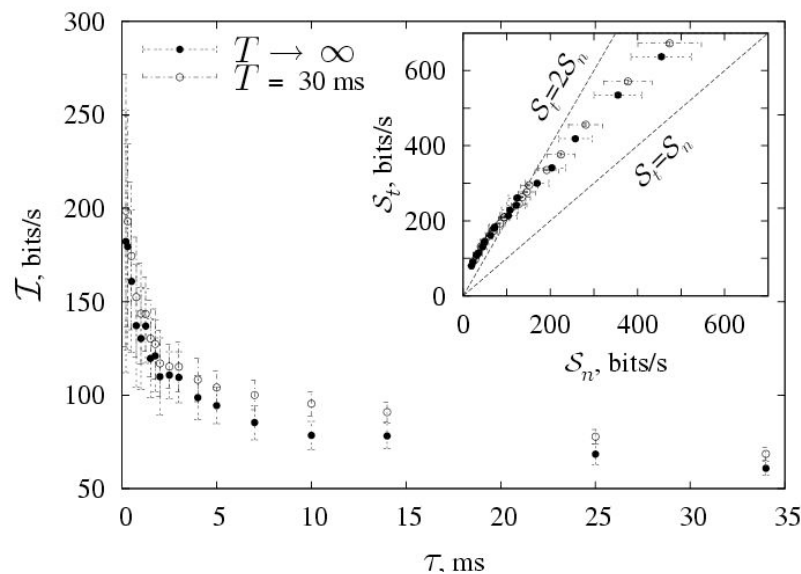
(Lewen, et al 2001)

In an upcoming paper we show that

$$I(s, r) = S(r) - \langle S(r | s) \rangle_s$$
$$= \lim_{T \rightarrow \infty} \frac{1}{2} \sum_{\omega} \log[1 + SNR(\omega)]$$

also grows with the light intensity.

Not just optimal estimation: just in time estimation!



(IN, Bialek, de Ruyter van Steveninck, 2005)

- An effort to make information available “now”
- Information grows with resolution

Why does the fly use such high resolution and short observation times to code this relatively slow signal?



A limited form of prediction

- Estimation of dynamical signal “right now” ($t=0$) from observations of its past ($t<0$).
- Need to know time statistics of the signal.

For a signal ϕ sampled at rate r and with $C(t) \xrightarrow{t \rightarrow 0} \sigma^2 \left(1 - \left(\frac{t}{\tau} \right)^v \right)^{1/(v+1)}$

$$\langle \delta^2 \phi \rangle = \left(\frac{t}{\tau} \right)^v + \frac{1}{rt} = \min \rightarrow t \sim \left(\frac{\tau^v}{r} \right)^{1/(v+1)}$$

Var of
decorrelation

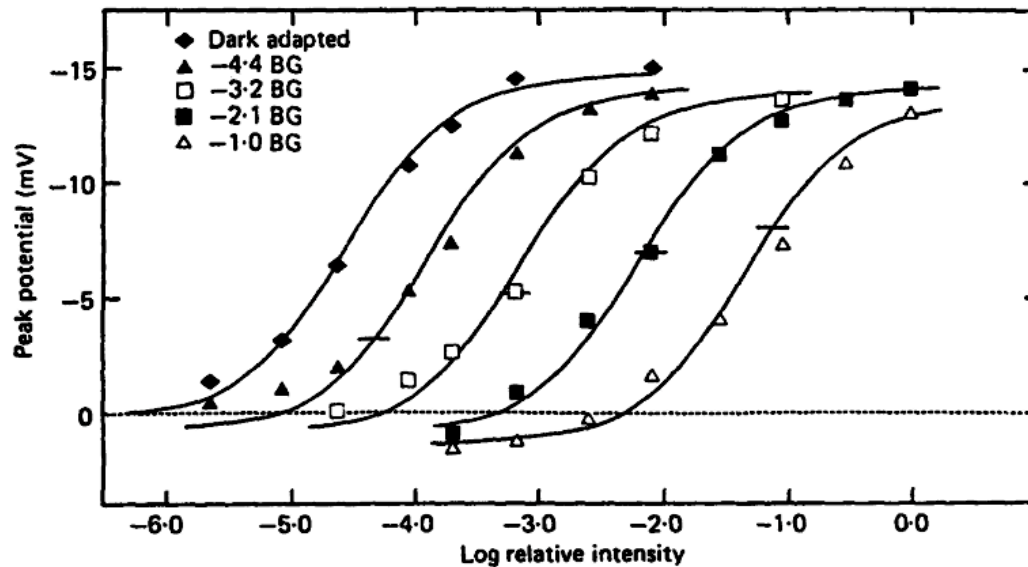
Var of the
mean



Motion prediction by fly

- Receptor delay (sampling) $\sim 10\text{ms}$
- Correlation time 100ms
- Efficient estimation $\sim 30\text{ms}$ (also behavioral response time of the fly)
- Thus ability to send most info in 30ms windows is not surprising
- For 30ms windows, coding at $< 1\text{ms}$ may be needed.

Turtle cone background light intensity adaptation

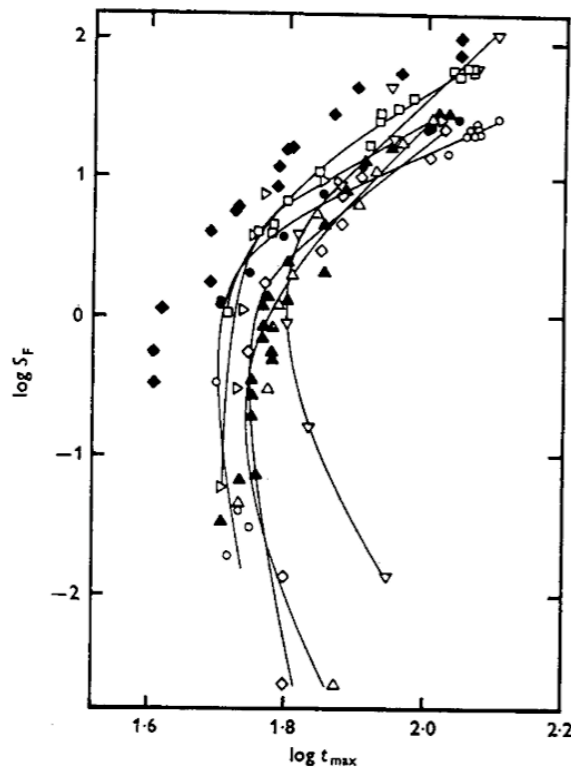


(Normann & Perlman, 1979)

Bckgr, log I	Adap, log I
dark	-4.4
-4.4	-3.8
-3.2	-3
-2.1	-2.3
-1	-1.3

$$I_a \propto I_0^{0.73}$$

Response time adaptation



(Baylor & Hodgkin, 1974)

$$\tau \propto I_0^{1/3 \dots 1/5}$$

Other animals range from 1/2 to 1/7.

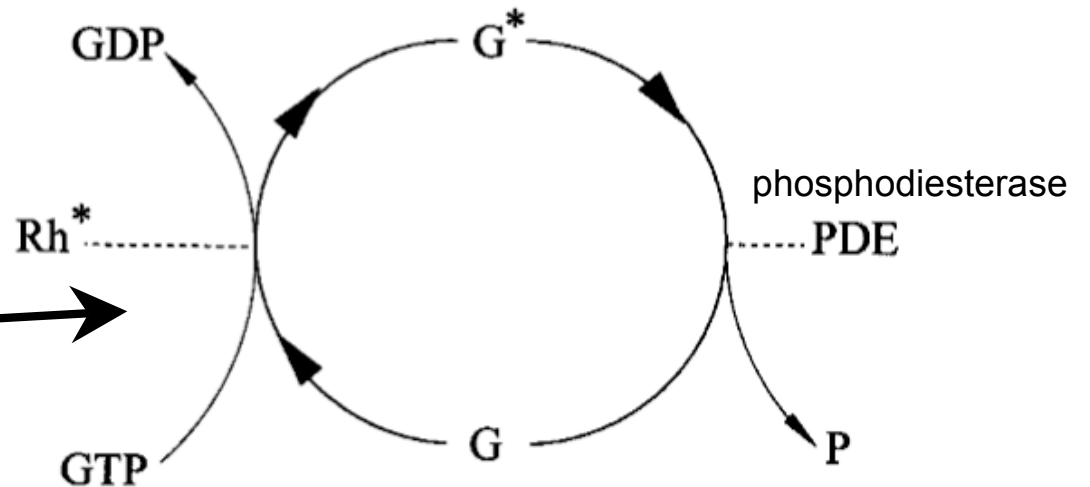
$$I_a \propto I_0 \tau$$

Probably not a coincidence:
Adapting to integrated flux.

What should τ be?

Cone: 3 low pass filters (at least):

- $\gamma + Rh \rightarrow Rh^*$
- $Rh^* \rightarrow PDE^*$
- $PDE^* \rightarrow GC$



$$\tau_R \frac{d\delta R}{dt} = -\delta R + g_R \left(\phi(t) + \eta_\phi(t) \right), \quad \phi = \log \frac{I}{I_0}, \quad \langle \eta_\phi(t) \eta_\phi(0) \rangle = 1 / I_0 \delta(t)$$

$$\tau_P \frac{d\delta P}{dt} = -\delta P + g_P \left(\delta R + \eta_R(t) \right), \quad \dots$$

...

Solution

(for signal-limited precision)

Represent SDE's as SFT, integrate out all fields except fields at moment $t=0$. Get

$$I_0 \equiv I[\phi(t=0); v(t=0)] = \log \frac{\langle \phi^2 \rangle}{\langle \phi^2 \rangle - \frac{\prod g_i^2 \langle \phi_f^2 \rangle^2}{\langle v^2 \rangle}}$$

Note that this is not same as

$$I[\phi(t); v(t)] = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T/2}^{T/2} \frac{d\omega}{2\pi} \log(1 + SNR(\omega))$$

which is the channel capacity.

Solution

(for signal-limited precision)

Represent SDE's as SFT, integrate out all fields except fields at moment $t=0$. Get

$$I_0 \equiv I[\phi(t=0); v(t=0)] = \log \frac{\langle \phi^2 \rangle}{\langle \phi^2 \rangle - \frac{\prod g_i^2 \langle \phi_f^2 \rangle^2}{\langle v^2 \rangle}}$$

Can also maximize total predictive information:

$$I[\phi(t > 0); v(t \leq 0)]$$

Finding τ

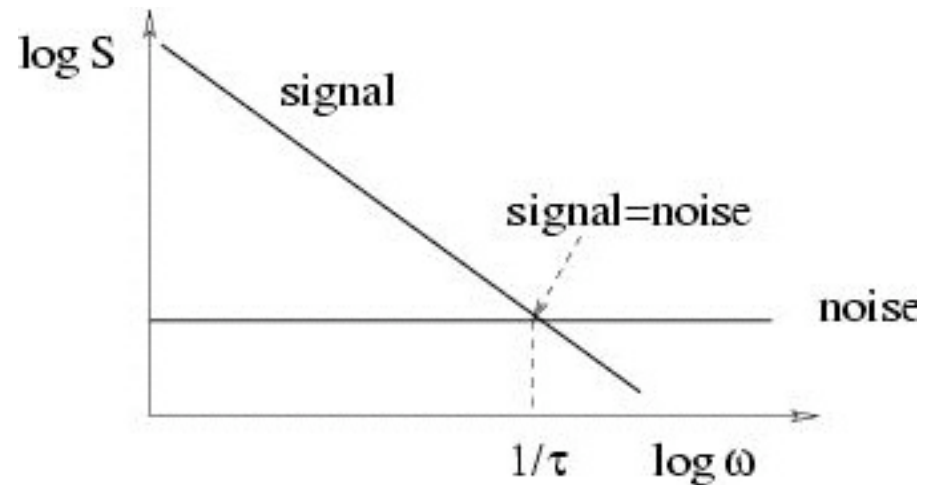
Maximize I_0 w.r.t τ

For:

$$S_{\phi}(\omega) \xrightarrow{\omega \rightarrow \infty} \omega^{-\alpha}$$

get:

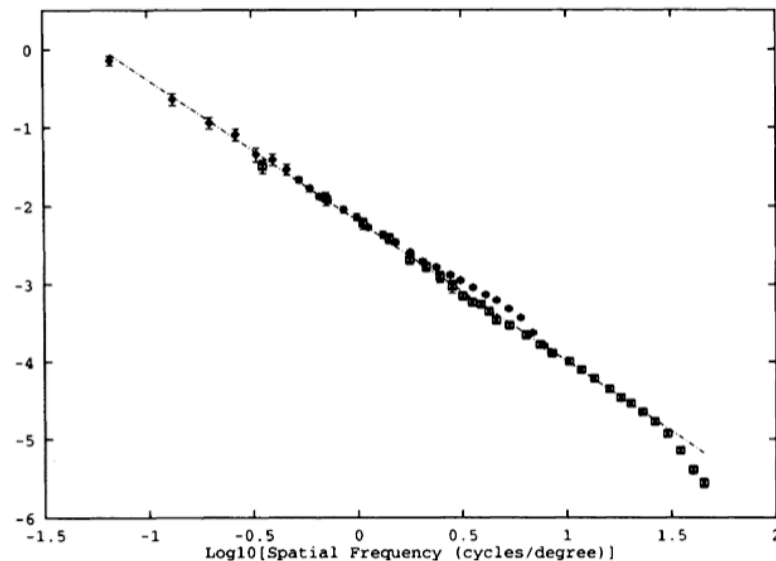
$$\tau \sim I_0^{-1/\alpha}$$



Best possible matched filter
(limited by biochemical mechanisms)

Also predicted by variance balance argument.

A problem



(Ruderman & Bialek, 1994)

- $1/k^{2-\varepsilon}$ spatial spectrum
- ~ 10 phoreceptors/fixation drift
- $1/\omega^{2-\varepsilon}$ temporal spectrum
- Should have $\tau \sim I_0^{-1/2}$

Wrong! But...



Biochemical constraint

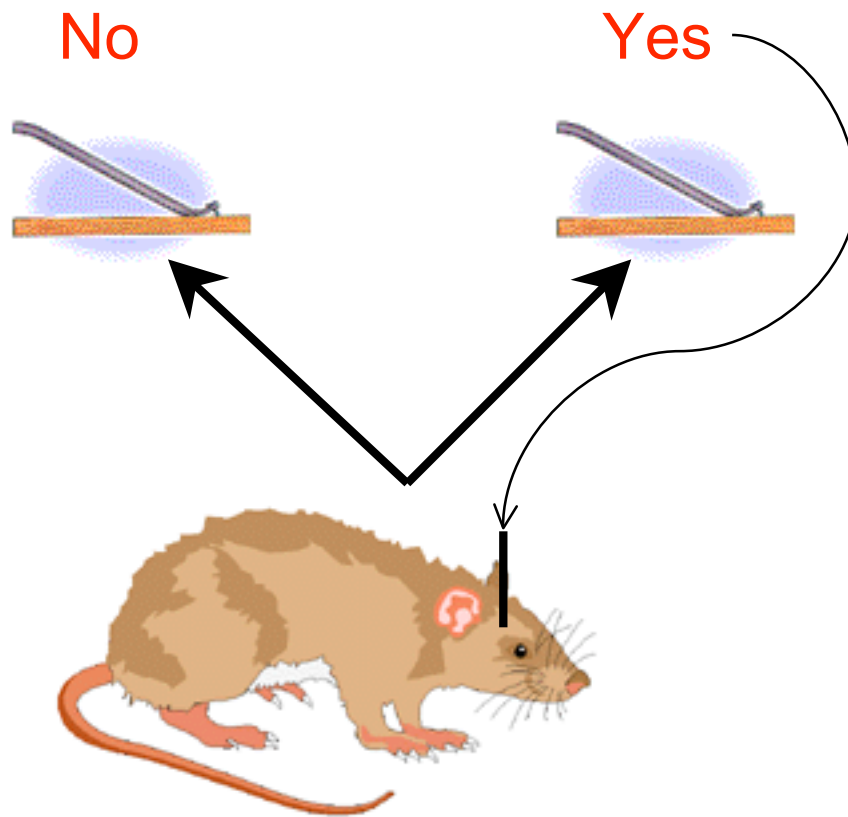
Rh* is the signal, its temporal response is uncontrollable (and badly known - Rieke & Baylor, 1998)

$$S_{Rh^*} \sim \frac{1}{\omega^2} S_\phi \sim \frac{1}{\omega^4}$$

Given this signal, the rest of the biochemistry should adapt in agreement with experiment

$$\tau \sim I_0^{-1/4}$$

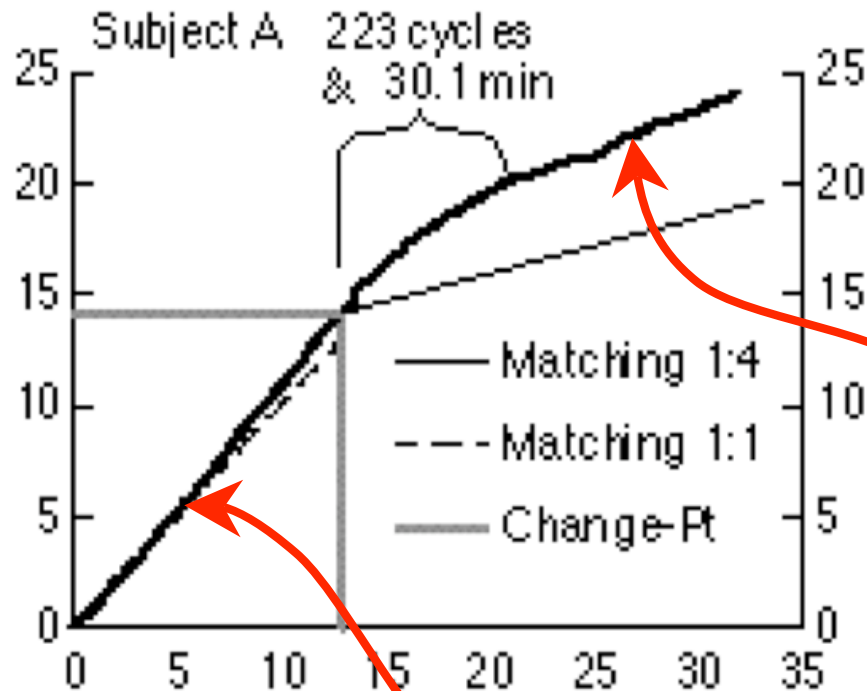
Rat matching experiments



(with Gallistel)

- Poisson deposition of rewards
- Rewards do not accumulate
- Possibly variable rate
- Changeover delay
- Rat matches

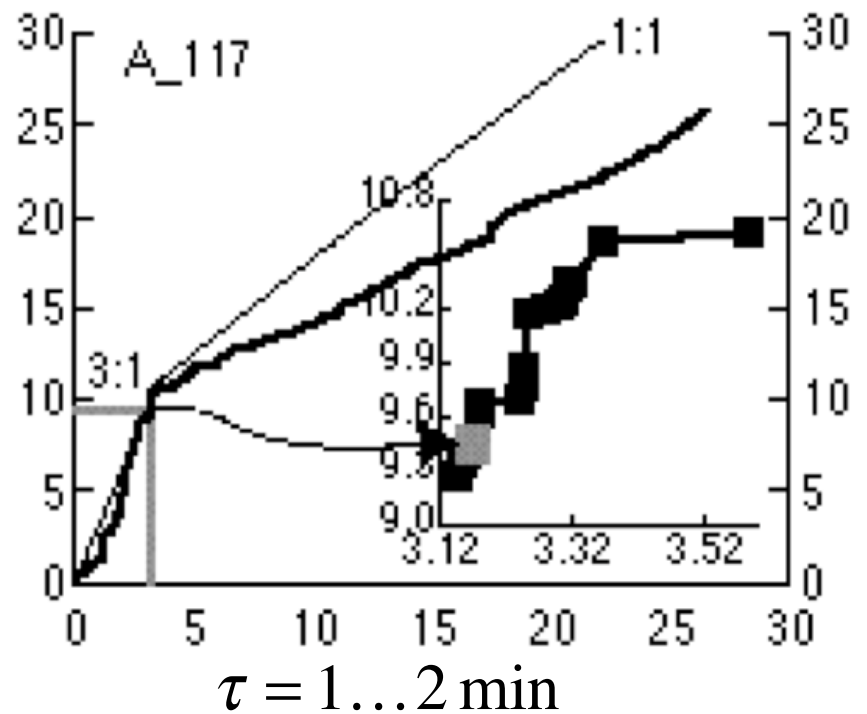
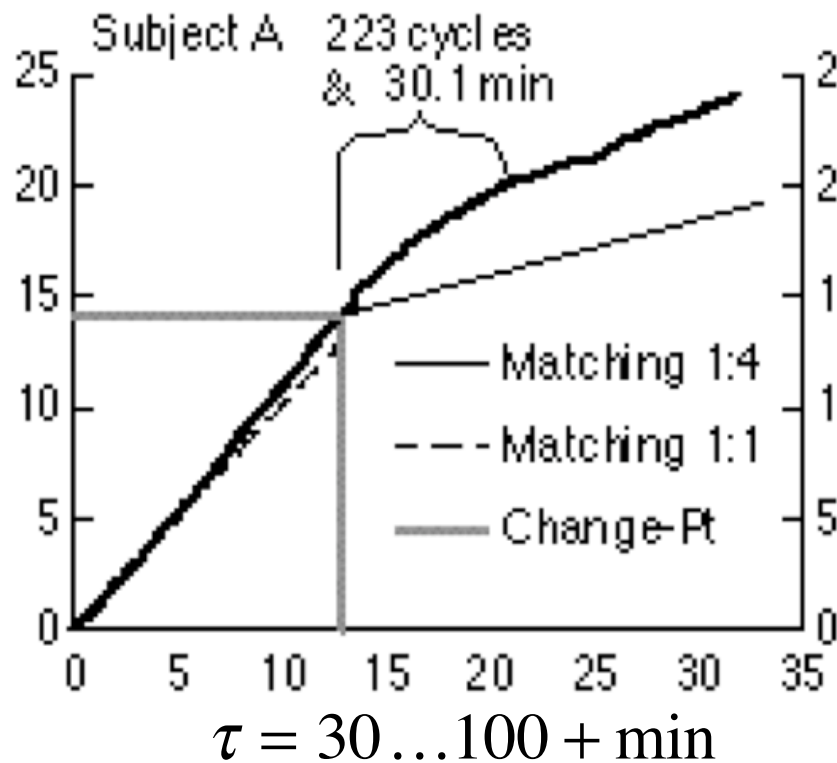
Rat matching experiments



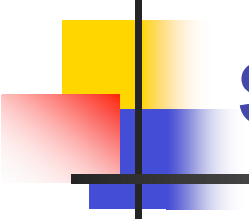
(Gallistel et al 2001)

- Poisson deposition of rewards
- Rewards do not accumulate
- Possibly variable rate
- Changeover delay
- Rat matches

But: Time scales are history dependent. Can we explain?



(also note imperfect matching)



Can we explain the time scales

$$P[\phi(t)] \propto \exp\left[-\frac{l}{2} \int (\partial_t \phi)^2 dt\right], \quad \phi(t) = \log r(t)$$

Sampling from a target $\theta(t) \rightarrow \phi_i$ at t_i

$$P[\phi(t) | \{x_i\}, \{t_i\}] \propto \exp\left[-\frac{l}{2} \int dt (\partial_t \phi)^2 - \sum_i V(\phi_i - \phi(t_i))\right]$$

Evolution in a random (time and space) potential



Examples of potentials

Poisson process:

$$\sum_i V_i = \int dt e^{\phi(t)} - \sum_i \phi(t_i) \rightarrow \int dt e^{\phi(t)} - \int dt e^{\theta(t)} \phi(t)$$

Learning a fluctuating mean of a Gaussian:

$$\sum_i V_i = \sum_i \frac{1}{2\sigma^2} (\phi(t_i) - \phi_i)^2 \rightarrow \frac{1}{2\sigma^2} \int dt r(t) (\phi - \theta)^2$$

In general, for fast sampling rate:

$$\sum_i V_i \rightarrow \int dt r(t) V(\phi - \theta)^2 \rightarrow r \int dt V(\phi - \theta)^2$$



Learning a Poisson variable

$$l \frac{d^2 \phi_0}{dt^2} = e^{\phi_0} - \sum_i \delta(t - t_i)$$

See also Bialek,
Callan, & Strong, 1996,
Nemenman and Bialek,
2002

$$\langle \delta^2 \phi_0 \rangle \approx \frac{1}{4} \frac{1}{\sqrt{e^\theta l}} \quad (\text{WKB, for large } e^\theta l)$$

Compare to the crude estimate above:

$$\tau \sim \sqrt{\frac{l}{e^\theta}}, \quad \langle \delta^2 \phi_0 \rangle \sim \frac{1}{\sqrt{e^\theta l}}$$



Time scales

Correlation time: $\tau \propto \sqrt{l / r}$

For stable period ($\tau_0 \sim 1$ hr):

$$l \approx 3 \cdot 10^6 s, \quad r \approx 1 / 10 s^{-1}, \quad \tau \sim 5 \cdot 10^3 s \approx 1.5 \text{ hrs}$$

For variable schedule ($\tau_0 \sim 1$ min):

$$l \approx 1800 s, \quad r \approx 1 / 10 s^{-1}, \quad \tau \sim 130 s \approx 2 \text{ min}$$

For monkeys (Sugrue et al, 2004) ($\tau_0 \sim 17$ samples):

$$l \approx 300 / r, \quad r, \quad \tau \sim 15 \text{ samples}$$

Importantly, estimate starts to
change immediately in both cases



Self-consistent estimation of l

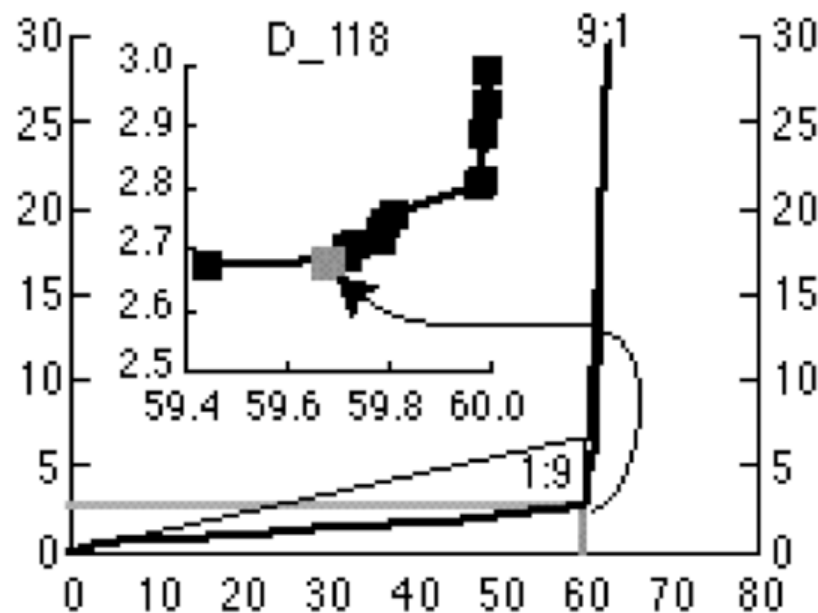
Averaging over $P[l]$ leads to correct estimation of the smoothness scale for fixed l (Nemenman and Bialek, 2002) if one takes into the account first loop corrections around ϕ_0 .

For time-dependent l :

$$P[l] \propto \exp \left[- \int dt \, l (\partial_t \log l)^2 \right]$$

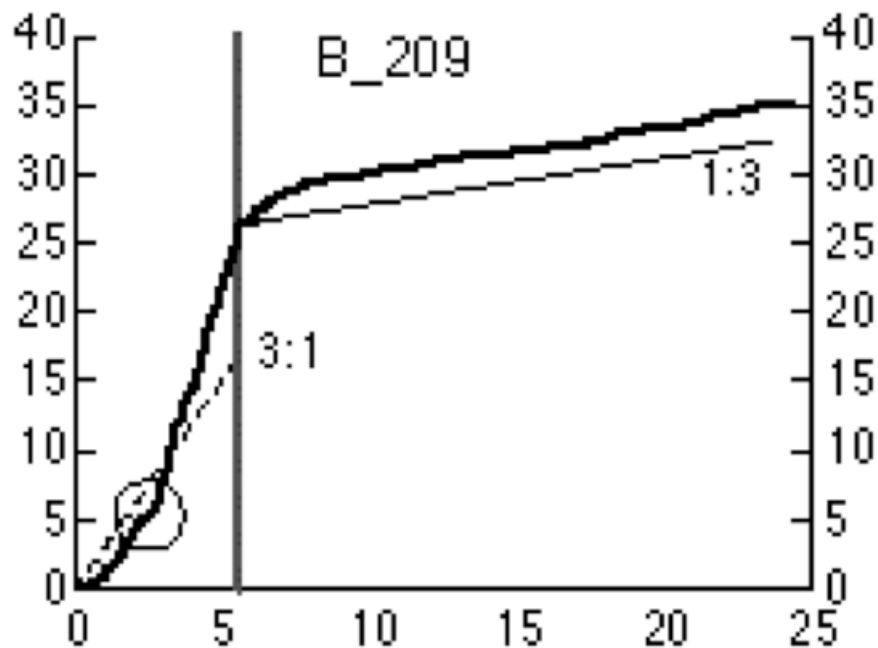
leads to self-consistent selection of l . Do not investigate particular form due to lack of data.

Abrupt changes



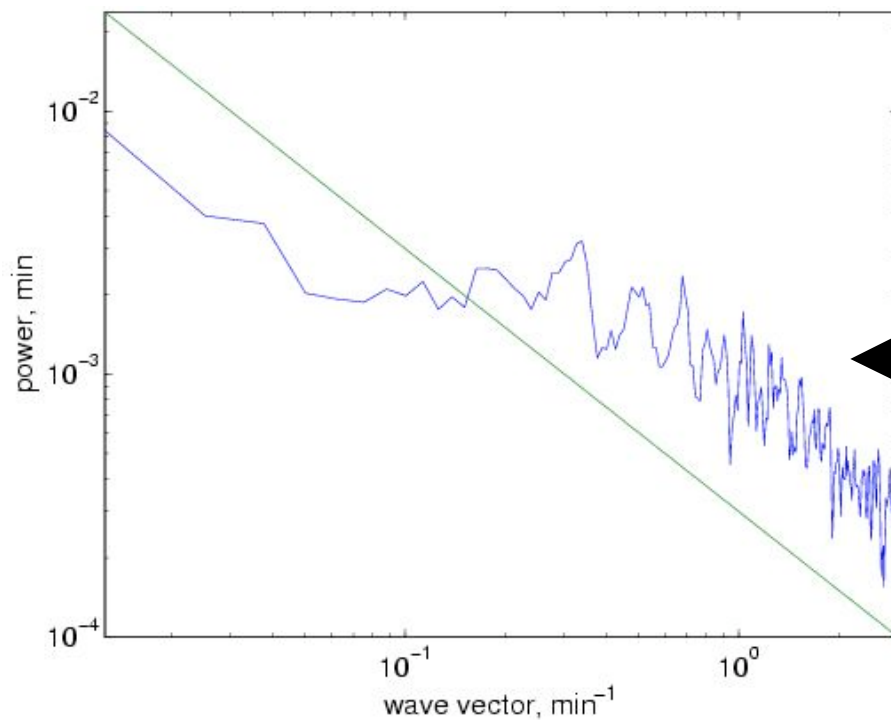
- Only after a few changes have been experienced
- Common during fast changes epochs

Abrupt changes



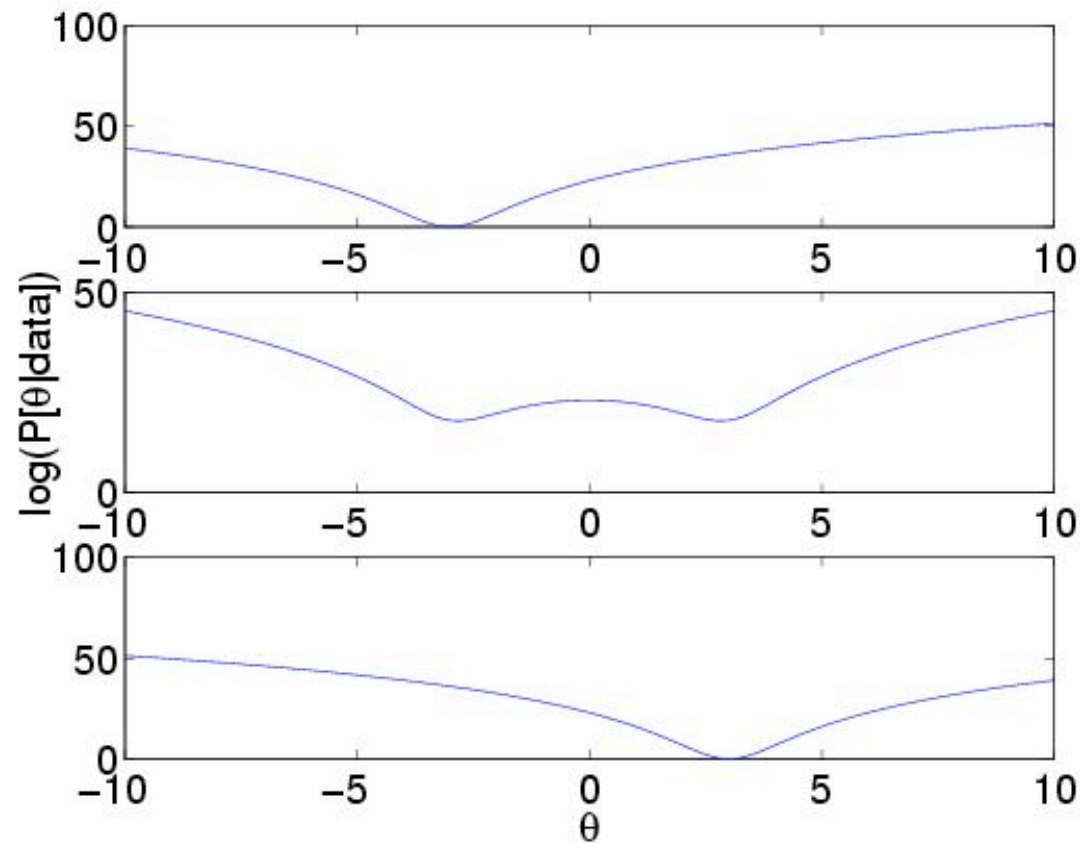
- Only after a few changes have been experienced
- Common during fast changes epochs
- Sometimes “unwarranted”
- Metastable states?

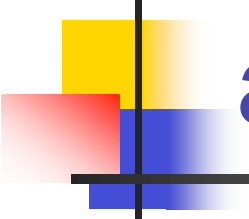
Caused by memory (non-local QFT)



- Overestimation of rate immediately leads to higher rate and persists
- Nonlocality, friction (see also Atwal, Bialek, 2004)
- Power spectrum of reward histories
- Two regimes clearly seen
- Peak at 0 - long range correlations

Memory, metastability, and non-Gaussianity



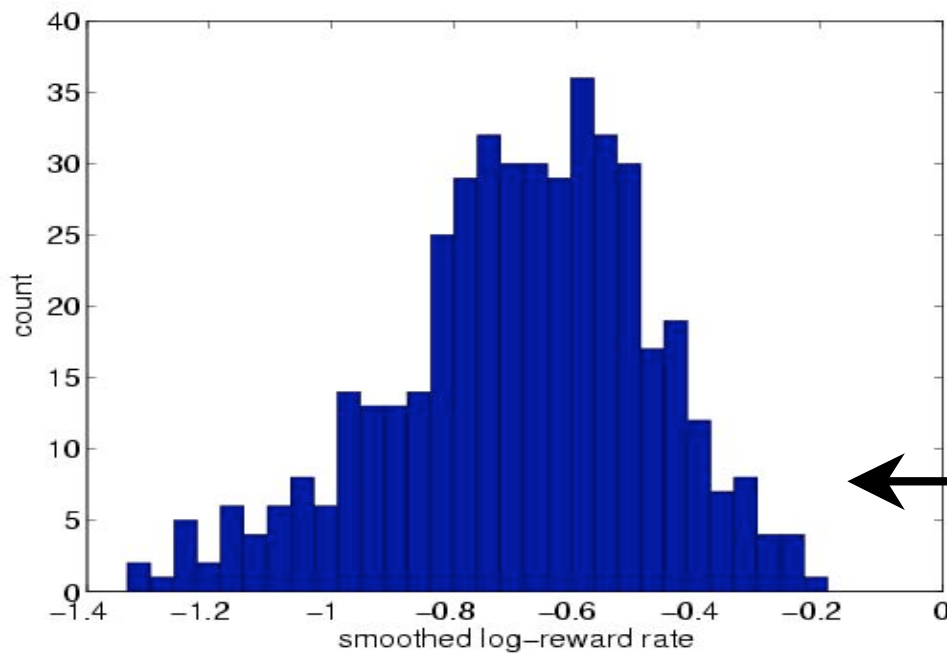


Modeling memory: two scales and rapid readjustments

- Need memory scale (long), and adaptation scale (short)
- Signal changes on long time scale, while effects of self-perpetuation of rate are on shorter scales

$$P[\phi, \psi \mid \text{data}] \propto \exp \left[-\frac{\lambda}{2} \int dt (\partial_t \psi)^2 - \int dt W(\phi - \psi) - \dots \right. \\ \left. -\frac{l}{2} \int dt (\partial_t \phi)^2 - \sum_i V(\phi_i - \phi(t_i)) \right]$$

Non-Gaussianity



- V is not quadratic in ϕ , plateaus (self-confounding effects); exact form unclear
- W is not quadratic either; left plateau; no exact form

$$\left. \frac{\partial^2}{\partial x^2} \right|_{x=0} V(x) = \mu^2$$

$$\left. \frac{\partial^2}{\partial x^2} \right|_{x=0} W(x) = m^2$$



Dynamics of fast field

The field undergoes small fluctuations (zero point and due to irregular sampling) near the minimum of the energy

$$l \frac{d^2 \phi_0}{dt^2} = 0 = e^\theta \frac{\partial V(\phi_0 - \theta)}{\partial \phi_0} + \frac{\partial W(\phi_0 - \psi)}{\partial \phi_0}$$



Two minima

For long-tailed distributions, will have two minima

$$\phi_0^{(1)} = \psi + \varepsilon_1(\theta - \psi)$$

$$\phi_0^{(2)} = \theta + \varepsilon_2(\psi - \theta)$$

Barrier depends on the shape and vanishes
as

$$\psi \rightarrow \theta$$

Jumps possible from a metastable state near ψ to
new minimum near θ .



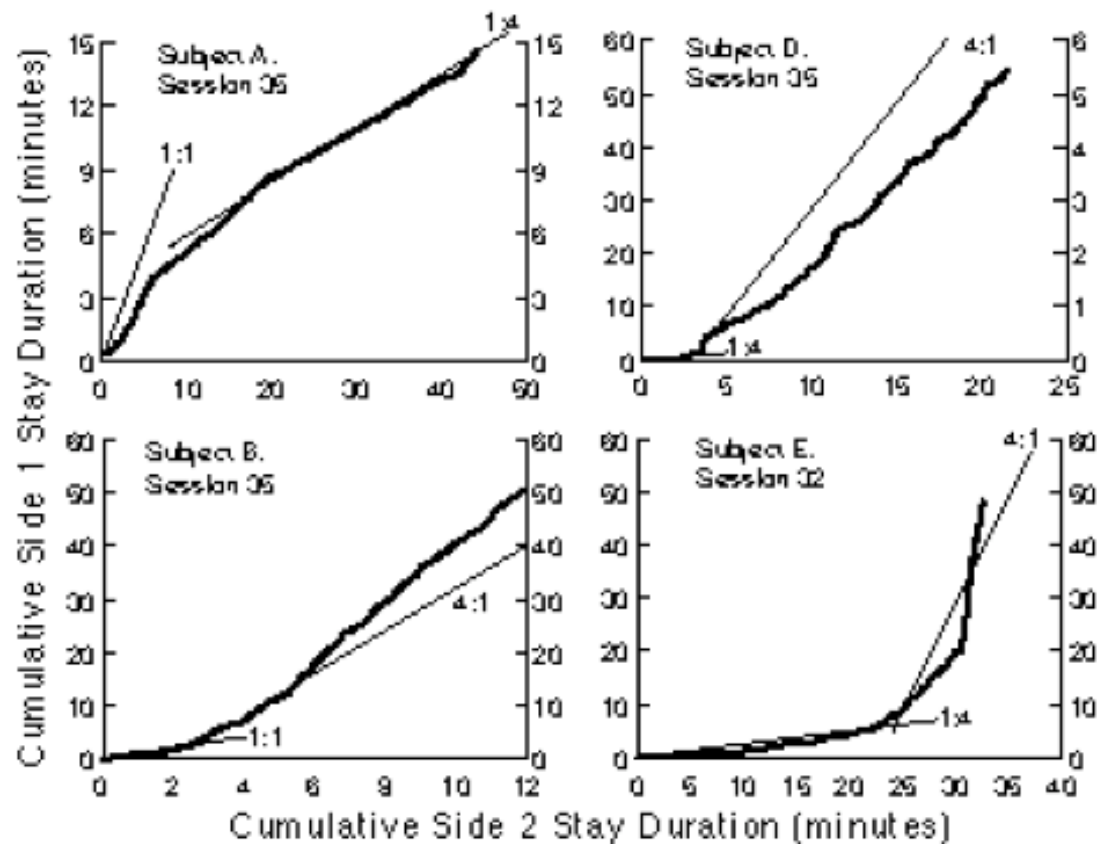
Adiabatic dynamics of the slow field

$$P[\psi \mid \text{data}] \propto \exp \left[-\frac{\lambda}{2} \int dt (\partial_t \psi)^2 - \int dt W(\phi_0^{(i)}(t) - \psi(t)) \right]$$

Either self-perpetuates, or approached the true solution (depending on which minima the fast field is in).

Critical periods?

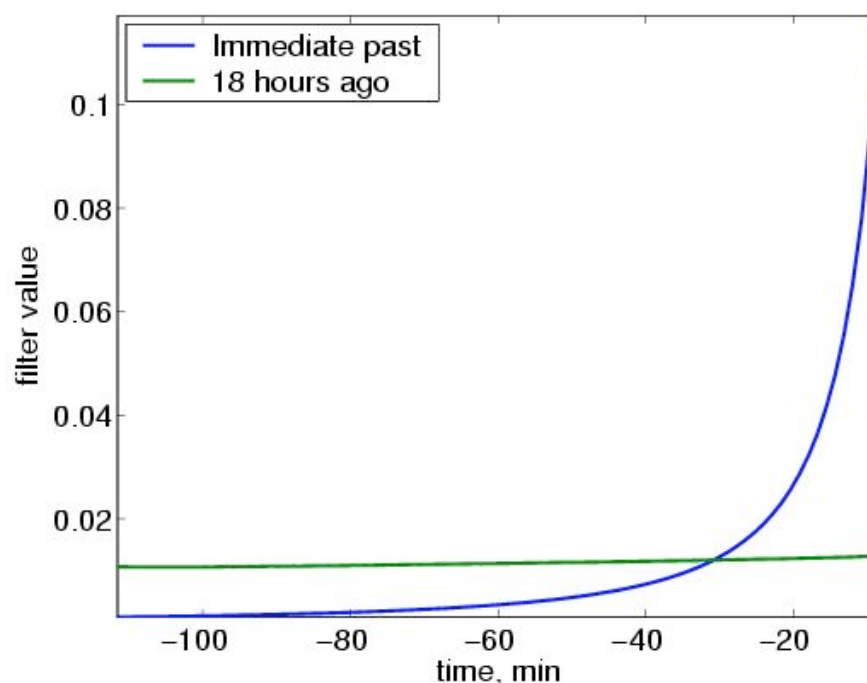
Reversal to status quo ante



Modeling memory: nonlocality and long range correlations

Bialek & Zee, 1990 - decoding can be done linearly accurately (even if the process itself is very nonlinear). Also trivially true for Gaussian processes.

$$\phi(t) = \sum_{t_i < t} F(t_i - t)$$



Optimal $F(t)$ for a Gaussian process with $C \sim t^2$ for a range near $t=0$ and $t=18\text{hrs}$ (normalized within the window).



Long-tailed filters explain reversal

- At the end of the session, rate estimates are effected mostly by the last (post-change) observation
- After a long delay, pre-change and post-change observations are almost equally weighed, but there are much more of the former.
- Wouldn't work for exponential filters as used by Sugrue et al, 2004.
- Experiments to measure $C(t)$ are now done.



Why matching?

- Matching is a bit suboptimal for maximizing reward.
- Matching is almost optimal for tracking rate changes.
- Can it be that the bit value of a reward is higher than its food value? (Rats are curious!)
- Preliminary support: matching for accumulating rewards. Planning experiments to test matching to neutral stimuli.