# Predictive information: From definition to applications to biological systems 

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Thanks to: William Bialek, Naftali Tishby

$$
\begin{gathered}
\text { physics/0007070 } \\
\text { physics/0103076 } \\
\text { q-bio/0402029 }
\end{gathered}
$$

## Outline

- A curious observation.
- Quantifying predictability and complexity.
- Predictability and optimization in sensory information processing.
- Learning and predictive information.
- Testing models used by animals.
- Bonus material.


## Entropy of words in a spin chain

$$
\begin{aligned}
& \downarrow \downarrow \downarrow \downarrow \uparrow \uparrow \uparrow \downarrow \downarrow \uparrow \uparrow \uparrow \downarrow \downarrow \downarrow \downarrow \downarrow \downarrow \downarrow
\end{aligned}
$$

$$
\begin{aligned}
& \begin{array}{c}
\mathrm{W}_{0}=\begin{array}{llll}
0 & 0 & 0 & 0 \\
\mathrm{~W}_{1}= & 0 & 0 & 0
\end{array} 1 \\
\mathrm{~W}_{2}=\begin{array}{llll}
0 & 0 & 1 & 0
\end{array} \\
\cdots \\
\mathrm{~W}_{15}= \\
1
\end{array} 1 \begin{array}{llll}
1 & 1 & 1
\end{array} \\
& \mathrm{~W}_{0} \quad \mathrm{~W}_{1} \ldots \mathrm{~W}_{9} \ldots \mathrm{~W}_{7} \ldots \mathrm{~W}_{0} \quad \mathrm{~W}_{1}
\end{aligned}
$$

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\begin{aligned}
& \downarrow \downarrow \downarrow \downarrow \uparrow \uparrow \uparrow \downarrow \downarrow \uparrow \uparrow \uparrow \downarrow \downarrow \downarrow \downarrow \downarrow \uparrow \\
& \mathrm{W}_{0}=0000
\end{aligned}
$$

$$
\begin{aligned}
& \mathrm{W}_{1}=0001 \\
& \mathrm{~W}_{2}=0010 \\
& \mathrm{~W}_{15}=11111
\end{aligned}
$$

$$
S(N)=-\sum_{k=0}^{2^{N}-1} P_{N}\left(W_{k}\right) \log _{2} P_{N}\left(W_{k}\right)
$$

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S(N)=-\sum_{k=0}^{2^{N}-1} P_{N}\left(W_{k}\right) \log _{2} P_{N}\left(W_{k}\right)
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For this chain, $P\left(W_{0}\right)=P\left(W_{1}\right)=P\left(W_{3}\right)=P\left(W_{7}\right)=P\left(W_{12}\right)=P\left(W_{14}\right)=2$, $P\left(W_{8}\right)=P\left(W_{9}\right)=1$, and all other frequencies (probabilities) are zero. Thus, $S(4) \approx 2.95$ bits.

## Entropy of 3 generated chains

- $J_{\mathrm{ij}}=\delta_{\mathrm{i}, \mathrm{j}+1}$
- $J_{\mathrm{ij}}=J_{0} \delta_{\mathrm{i}, \mathrm{j}+1}, J_{0}$ is taken at random from $\mathcal{N}(0,1)$ every 400000 spins
- $J_{\mathrm{ij}}$ is taken at random from $\mathcal{N}\left(0, \frac{1}{\mathrm{i}-\mathrm{j}}\right)$ every 400000 spins
$1 \cdot 10^{9}$ spins total.



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Entropy is extensive!
It shows no distinction between the cases.

## Subextensive component of the entropy

. . . shows a qualitative distinction between the cases!


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Other examples:
const periodic, fully random, chaotic sequences (finite correlation length)
log systems at phase transitions, or at the onset of chaos (divergent correlation length)
power texts, DNA sequences, (likely) some exotic transitions, (many divergent correlation lengths)

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- Entropy density or channel capacity do not distinguish these cases.
- Theory of phase transitions may not distinguish between the last two cases.
- Complexity of underlying dynamics intuitively increases from const to power.


## Objectives

- unified description of complexity and learning
- make distinction between useful and unusable data
- do this using physical quantities
- understand models used by organisms to represent the world
- understand biological designs by means of optimization principles


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- we learn (estimate parameters, extrapolate, classify, ...) to generalize and predict from training examples; estimation of parameters is only an intermediate step


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- measuring organisms' learning and prediction performance for signals of different complexity may reveal the underlying models
- optimizing predictive information may be the design principle


## Quantifying predictability

Information theory: non-metric, universal way to quantify learning

| $T, N$ | 0 | $T^{\prime}, N^{\prime} \quad x$ |
| :---: | :---: | :---: |
| past | now | future |

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Information theory: non-metric, universal way to quantify learning

$$
\begin{array}{rcc}
T, N & 0 & T^{\prime}, N^{\prime} \quad x \\
\hline \text { past } & \text { now future } \\
\mathcal{I}_{\text {pred }}\left(T, T^{\prime}\right) & =\left\langle\log _{2}\left[\frac{P\left(x_{\text {future }} \mid x_{\text {past }}\right)}{P\left(x_{\text {future }}\right)}\right]\right\rangle \\
& =S(T)+S\left(T^{\prime}\right)-S\left(T+T^{\prime}\right)
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Predictability is a deviation from extensivity!

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I_{\text {pred }}(T) \equiv \mathcal{I}_{\text {pred }}(T, \infty)=S_{1}(T)
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- diminishing returns, $\lim _{T \rightarrow \infty} \frac{I_{\mathrm{pred}}(T)}{S(T)}=0$
- prediction and postdiction are symmetric
- it relates to and generalizes many relevant quantities
- learning: universal learning curves
- complexity: complexity measures
- coding: model coding length


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- learning finite-parameter densities
- well known as $I(N$, parameters $)=I_{\text {pred }}(N)$
- physical system at criticality
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$\lim _{N \rightarrow \infty} I_{\text {pred }}=$ const $\times N^{\xi}$ learning more features as $N$ grows
- learning continuous densities
- language
- some critical phenomena (wetting transitions)
- not well studied


## Which complexity do we want to define?

- complexity of dynamics that generates a time series (not computational or descriptive complexity); thus it must be zero for totally random and for easily predictable processes
- usable for Occam-style punishment in statistical inference
- expressible in conventional physical terms
- must be attached to an ensemble, not a single realization


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The divergent subextensive term measures complexity uniquely!

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- equivalence $=$ indistinguishable conditional distributions of futures

If sufficient statistics exist, then $C_{K} \approx I_{\text {pred }}$. Otherwise $C_{K}>I_{\text {pred }}$. $C_{K}$ is unique up to a constant.

## $I_{\text {pred }}$ optimization in biology



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$$
\tau \frac{d x}{d t}=-x+\phi(t)+\eta(t), \quad\langle\eta(t) \eta(0)\rangle=1 / I_{0} \delta(t)
$$

## $I_{\text {pred }}$ optimization in biology

$$
\begin{gathered}
\xrightarrow[\text { input, } \phi]{S_{\phi}(\omega) \propto \omega^{-\alpha}} \text { "bug" } \\
\tau \frac{d x}{d t}=-x+\phi(t)+\eta(t), \quad\langle\eta(t) \eta(0)\rangle=1 / I_{0} \delta(t) \\
\mathcal{I}([\phi],[x])=\lim _{T \rightarrow \infty} \frac{1}{2 T} \int_{-T / 2}^{T / 2} \frac{d \omega}{2 \pi} \log \left(1+\frac{S_{\phi}(\omega)}{1 / I_{0}}\right)
\end{gathered}
$$

Maximization w.r.t. $\tau$ is meaningless.

## $I_{\text {pred }}$ extraction and maximization


(Baylor and Hodgkin, 1974)

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$$
I\left(\left[x_{\text {past }}\right],\left[\phi_{\text {future }}\right]\right)-\text { too difficult }
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## $I_{\text {pred }}$ extraction and maximization

$I\left(\left[x_{\text {past }}\right],\left[\phi_{\text {future }}\right]\right)-$ too difficult

$$
I\left(x_{0}, \phi_{0}\right)=\log \frac{\left\langle\phi^{2}\right\rangle}{\left\langle\phi^{2}\right\rangle-\frac{\left\langle\phi_{f}^{2}\right\rangle^{2}}{\left\langle x^{2}\right\rangle}}
$$



(Baylor and Hodgkin, 1974)

## Fly H1 predictive information



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Estimate $I\left(\right.$ spikes $\left._{\text {past }}, v_{\text {future }}\right)$.
Close to maximum!

## Specific examples: problem setup

$Q(\vec{x} \mid \boldsymbol{\alpha})$ p. d. f. for $\vec{x}$ parameterized by unknown parameters $\boldsymbol{\alpha}$ $\operatorname{dim} \alpha=K$ dimensionality of $\alpha$, may be infinite $\mathcal{P}(\alpha)$ prior distribution of parameters
$\vec{x}_{1} \cdots \vec{x}_{\mathrm{N}}$ random samples from the distribution

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$\vec{x}_{1} \cdots \vec{x}_{\mathrm{N}}$ random samples from the distribution

$$
\begin{aligned}
P\left(\vec{x}_{1}, \vec{x}_{2}, \cdots, \vec{x}_{\mathrm{N}} \mid \boldsymbol{\alpha}\right) & =\prod_{\mathrm{i}=1}^{\mathrm{N}} Q\left(\vec{x}_{\mathrm{i}} \mid \boldsymbol{\alpha}\right) \\
P\left(\vec{x}_{1}, \vec{x}_{2}, \cdots, \vec{x}_{\mathrm{N}}\right) & =\int d^{K} \alpha \mathcal{P}(\boldsymbol{\alpha}) \prod_{\mathrm{i}=1}^{\mathrm{N}} Q\left(\vec{x}_{\mathrm{i}} \mid \boldsymbol{\alpha}\right) \\
S\left(\vec{x}_{1}, \vec{x}_{2}, \cdots, \vec{x}_{\mathrm{N}}\right) & \equiv S(N) \\
& =-\int d \vec{x}_{1} \cdots d \vec{x}_{\mathrm{N}} P\left(\left\{\vec{x}_{\mathrm{i}}\right\}\right) \log _{2} P\left(\left\{\vec{x}_{\mathrm{i}}\right\}\right)
\end{aligned}
$$

## Density of states

$$
\mathcal{E}_{N} \equiv \frac{1}{N} \sum_{i} \log \left[\frac{Q\left(\vec{x}_{\mathrm{i}} \mid \overline{\boldsymbol{\alpha}}\right)}{Q\left(\vec{x}_{\mathrm{i}} \mid \boldsymbol{\alpha}\right)}\right] \xrightarrow{\text { anneal }} \epsilon=\int d \vec{x} Q(\vec{x} \mid \overline{\boldsymbol{\alpha}}) \log \frac{Q(\vec{x} \mid \overline{\boldsymbol{\alpha}})}{Q(\vec{x} \mid \boldsymbol{\alpha})}
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Z(\overline{\boldsymbol{\alpha}} ; N)=\int d \epsilon \rho(\epsilon ; \overline{\boldsymbol{\alpha}}) \exp [-N \epsilon] \\
\rho(\epsilon ; \overline{\boldsymbol{\alpha}})=\int d^{K} \alpha \mathcal{P}(\boldsymbol{\alpha}) \delta\left[\epsilon-D_{\mathrm{KL}}(\overline{\boldsymbol{\alpha}}| | \boldsymbol{\alpha})\right]
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Annealed approximation (almost) always works. Learning is annealing at decreasing temperature. Nonzero $\rho \Longrightarrow$ consistency in learning.

## Density at $\epsilon \rightarrow 0, I_{\text {pred }}$, and learning

Occam factor, generalization error, prediction error, fluctuation determinant:

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\mathcal{D}(\overline{\boldsymbol{\alpha}} ; N) \approx-\log \int d \epsilon \rho(\epsilon ; \overline{\boldsymbol{\alpha}}) \mathrm{e}^{-N \epsilon}
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Universal learning curves:

$$
\begin{aligned}
\Lambda(\overline{\boldsymbol{\alpha}} ; N) & \equiv D_{\mathrm{KL}}\left(\overline{\boldsymbol{\alpha}} \| \boldsymbol{\alpha}_{\mathrm{est}}\right) \approx \frac{d \mathcal{D}(\overline{\boldsymbol{\alpha}} ; N)}{d N} \\
\Lambda(N) & \equiv \int d \overline{\boldsymbol{\alpha}} \mathcal{P}(\overline{\boldsymbol{\alpha}}) \Lambda(\overline{\boldsymbol{\alpha}} ; N) \approx \frac{d I_{\mathrm{pred}}}{d N}
\end{aligned}
$$

## Finite number of states and finite $I_{\text {pred }}$

$$
\rho\left(\epsilon ; a_{i}\right)=\sum_{j=1}^{M} \mathcal{P}_{j} \delta\left(d_{i j}-\epsilon\right)
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\mathcal{D}\left(a_{i} ; N\right) & =c_{1}-c_{2} \exp \left[-N c_{3}\right] \\
\Lambda\left(a_{i} ; N\right) & \approx c_{2} c_{3} \exp \left[-N c_{3}\right]
\end{aligned}
$$

$I_{\text {pred }}$ saturates as $N \rightarrow \infty$

## Power-law density function

$$
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Example: sound finite parameter models, $\operatorname{dim} \boldsymbol{\alpha}=d$.

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\rho(\epsilon ; \overline{\boldsymbol{\alpha}}) & \xrightarrow{\epsilon \rightarrow 0} \mathcal{P}(\overline{\boldsymbol{\alpha}}) \frac{2 \pi^{d / 2}}{\Gamma(d / 2)}(\operatorname{det} \mathcal{F})^{-1 / 2} \epsilon^{(d-2) / 2} \\
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Speed of approach to this asymptotics is rarely investigated.

## Another example

Learning $Q\left(\vec{x}_{1} \cdots \vec{x}_{\mathrm{N}} \mid \boldsymbol{\alpha}\right)$, a finite parameter Markov process with long range intrinsic correlations such that

$$
\begin{aligned}
S\left[\left\{\vec{x}_{\mathrm{i}}\right\} \mid \boldsymbol{\alpha}\right] & \equiv-\int d^{N} \vec{x} Q\left(\left\{\vec{x}_{\mathrm{i}}\right\} \mid \boldsymbol{\alpha}\right) \log _{2} Q\left(\left\{\vec{x}_{\mathrm{i}}\right\} \mid \boldsymbol{\alpha}\right) \\
& \rightarrow N \mathcal{S}_{0}+\mathcal{S}_{0}^{*} ; \quad \mathcal{S}_{0}^{*}=\frac{K^{\prime}}{2} \log _{2} N
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S\left[\left\{\vec{x}_{\mathrm{i}}\right\} \mid \boldsymbol{\alpha}\right] & \equiv-\int d^{N} \vec{x} Q\left(\left\{\vec{x}_{\mathrm{i}}\right\} \mid \boldsymbol{\alpha}\right) \log _{2} Q\left(\left\{\vec{x}_{\mathrm{i}}\right\} \mid \boldsymbol{\alpha}\right) \\
& \rightarrow N \mathcal{S}_{0}+\mathcal{S}_{0}^{*} ; \quad \mathcal{S}_{0}^{*}=\frac{K^{\prime}}{2} \log _{2} N \\
S_{1}^{(\mathrm{a})}(N) & \approx \frac{K+K^{\prime}}{2} \log _{2} N
\end{aligned}
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## Another example

Learning $Q\left(\vec{x}_{1} \cdots \vec{x}_{\mathrm{N}} \mid \boldsymbol{\alpha}\right)$, a finite parameter Markov process with long range intrinsic correlations such that

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Do not distinguish predictability from unknown parameters and from intrinsic correlations.
In physics similar to: order parameters $\Longleftrightarrow$ interactions.

## RG, not finite size scaling!



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$$
S(N)=S(\text { block })+S(\text { spin } \mid \text { block })
$$

Scaling fields carry information across.
Is $I_{\text {pred }}=f$ (scaling exponents) $\log N$ ?

## Essential singularity in the density

$$
\begin{aligned}
\rho(\epsilon \rightarrow 0 ; \overline{\boldsymbol{\alpha}}) & \approx A(\overline{\boldsymbol{\alpha}}) \exp \left[-\frac{B(\overline{\boldsymbol{\alpha}})}{\epsilon^{\mu}}\right], \quad \mu>0 \\
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- finite parameter model with increasing number of parameters $K \sim$ $N^{\mu /(\mu+1)} ; S_{1}(N) \sim N^{\mu / \mu+1}$, not $S_{1}(N) \sim \frac{N^{\mu / \mu+1}}{2} \log N$
- as $\mu \rightarrow \infty$ complexity grows and then vanishes to the leading order when $S_{1}^{(\mathrm{a})}$ becomes extensive


## Example of the power-law $I_{\text {pred }}$

Learning a smooth nonparameteric density $Q(x)=1 / l_{0} \mathrm{e}^{-\phi(x)}$, $x \in[0, L]$ (Bialek, Callan, and Strong 1996).

$$
\mathcal{P}[\phi(x)]=\frac{1}{\mathcal{Z}} \exp \left[-\frac{l}{2} \int d x\left(\frac{\partial \phi}{\partial x}\right)^{2}\right] \delta\left[\frac{1}{l_{0}} \int d x \mathrm{e}^{-\phi(x)}-1\right]
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- increasing number of "effective parameters" (bins) of adaptive size $\sim \sqrt{l / N Q(x)}$
- heuristic arguments for the dimensionality $\zeta$ and the smoothness exponent $\eta$ give $S_{1}(N) \sim N^{\zeta / 2 \eta}$ - demonstrates a crossover from complexity to randomness


## Which model is being used?

for QFT or nested asymptotics kicks in fast

- asymptotic decay rate should signify the model


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for QFT or nested asymptotics kicks in fast

- asymptotic decay rate should signify the model
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maybe FDT? $\frac{\partial \Lambda}{\partial N}=-\zeta_{N} \Lambda^{\nu}$


## Fluctuations (drifting target) and dissipation (learning curve)


(Fairhall et al., 2001)

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(Fairhall et al., 2001)

$$
\Delta_{\mathrm{rms}}=\left\{\nu^{1 / \nu} \frac{\Gamma\left(\frac{3}{2 \nu}\right)}{\Gamma\left(\frac{1}{2 \nu}\right)}\right\}^{1 / 2}\left(\frac{\Omega}{\zeta}\right)^{1 /(2 \nu)}
$$

## What's next?

extraction separating predictive information from non-predictive using the Information Bottleneck technique
physics of phase transitions, connection to subextensive statistical mechanics
learning unification of approaches: Bayesian, SRM, MDL, CuckerSmale. . .
biology what is predictive information of natural symbolic sequences (DNA, languages, spike trains)? animal behavior? can we understand molecular circuits in terms of learning (extracting $I_{\text {pred }}$ ?
dynamical systems theory what is predictive information and complexity of various systems?

