Predictive information: From definition to applications to biological systems

Ilya Nemenman

KITP, UCSB

Thanks to: William Bialek, Naftali Tishby

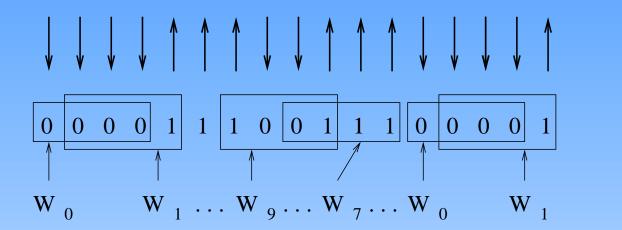
physics/0007070
physics/0103076
q-bio/0402029



Outline

- A curious observation.
- Quantifying predictability and complexity.
- Predictability and optimization in sensory information processing.
- Learning and predictive information.
- Testing models used by animals.
- Bonus material.

Entropy of words in a spin chain



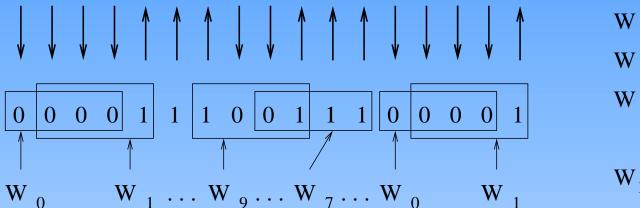
$$W_0 = 0 \ 0 \ 0 \ 0$$

$$W_1 = 0 \ 0 \ 0 \ 1$$

$$W_2 = 0 \ 0 \ 1 \ 0$$

$$W_{15} = 1 \ 1 \ 1 \ 1$$

Entropy of words in a spin chain



$$W_{0} = 0 \ 0 \ 0 \ 0$$

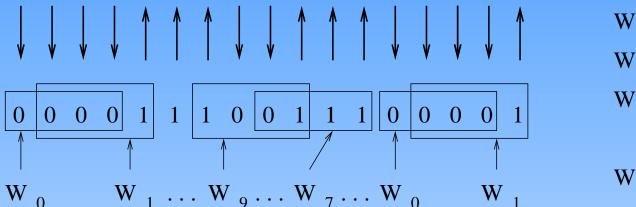
$$W_{1} = 0 \ 0 \ 0 \ 1$$

$$W_{2} = 0 \ 0 \ 1 \ 0$$

$$W_{15} = 1 \ 1 \ 1 \ 1$$

$$S(N) = -\sum_{k=0}^{2^{N}-1} P_{N}(W_{k}) \log_{2} P_{N}(W_{k})$$

Entropy of words in a spin chain



$$W_{0} = 0 \ 0 \ 0 \ 0$$

$$W_{1} = 0 \ 0 \ 0 \ 1$$

$$W_{2} = 0 \ 0 \ 1 \ 0$$

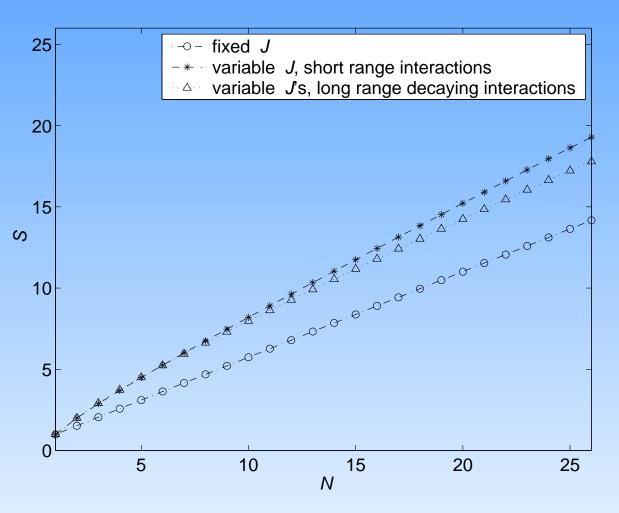
$$W_{15} = 1 \ 1 \ 1 \ 1$$

$$S(N) = -\sum_{k=0}^{2^{N}-1} P_{N}(W_{k}) \log_{2} P_{N}(W_{k})$$

For this chain, $P(W_0) = P(W_1) = P(W_3) = P(W_7) = P(W_{12}) = P(W_{14}) = 2$, $P(W_8) = P(W_9) = 1$, and all other frequencies (probabilities) are zero. Thus, $S(4) \approx 2.95 \text{ bits}$.

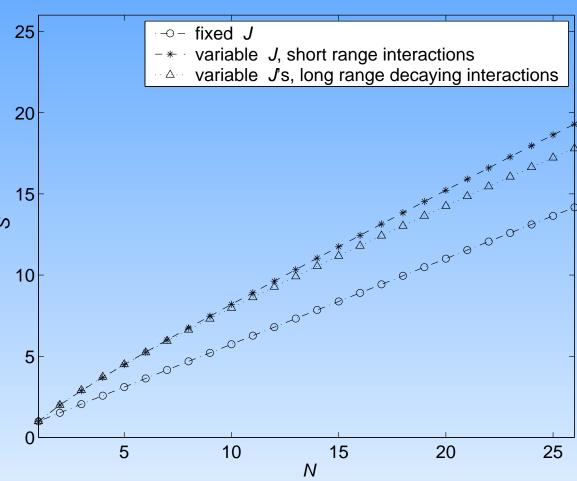
Entropy of 3 generated chains

- $J_{ij} = \delta_{i,j+1}$
- $J_{\rm ij}=J_0\,\delta_{\rm i,j+1}$, J_0 is taken at random from $\mathcal{N}(0,1)$ every 400000 spins
- J_{ij} is taken at random from $\mathcal{N}(0,\frac{1}{\mathbf{i}-\mathbf{j}})$ every 400000 spins
- $1 \cdot 10^9$ spins total.



Entropy of 3 generated chains

- $J_{ij} = \delta_{i,j+1}$
- $J_{\rm ij}=J_0\,\delta_{\rm i,j+1}$, J_0 is taken at random from $\mathcal{N}(0,1)$ every 400000 spins
- J_{ij} is taken at random from $\mathcal{N}(0,\frac{1}{\mathbf{i}-\mathbf{j}})$ every 400000 spins
- $1 \cdot 10^9$ spins total.

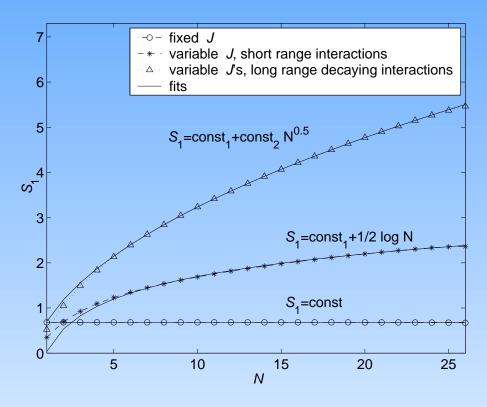


Entropy is extensive!

It shows no distinction between the cases.

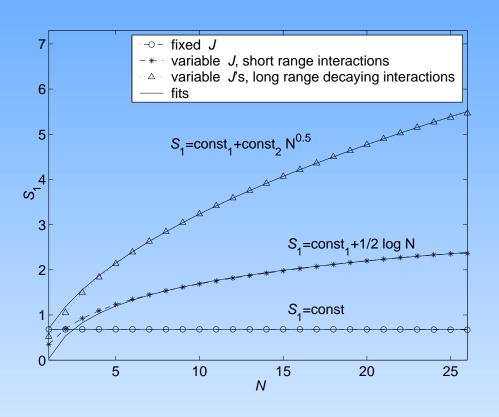
Subextensive component of the entropy

... shows a qualitative distinction between the cases!



Subextensive component of the entropy

... shows a qualitative distinction between the cases!



Other examples:

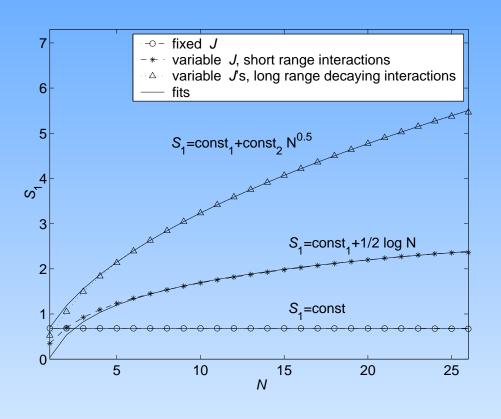
const periodic, fully random,
 chaotic sequences (finite
 correlation length)

log systems at phase transitions, or at the onset of chaos (divergent correlation length)

power texts, DNA sequences, (likely) some exotic transitions, (many divergent correlation lengths)

Subextensive component of the entropy

... shows a qualitative distinction between the cases!



Other examples:

const periodic, fully random,
 chaotic sequences (finite
 correlation length)

log systems at phase transitions, or at the onset of chaos (divergent correlation length)

power texts, DNA sequences,
 (likely) some exotic transitions, (many divergent
 correlation lengths)

- Entropy density or channel capacity do not distinguish these cases.
- Theory of phase transitions may not distinguish between the last two cases.
- Complexity of underlying dynamics intuitively increases from const to power.

Objectives

- unified description of complexity and learning
- make distinction between useful and unusable data
- do this using physical quantities
- understand models used by organisms to represent the world
- understand biological designs by means of optimization principles

 we learn (estimate parameters, extrapolate, classify, ...) to generalize and predict from training examples; estimation of parameters is only an intermediate step

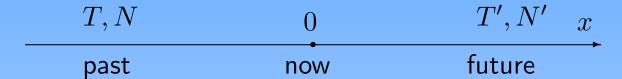
- we learn (estimate parameters, extrapolate, classify, ...) to generalize and predict from training examples; estimation of parameters is only an intermediate step
- nonpredictive features in any signal are useless since we observe now and react in the future

- we learn (estimate parameters, extrapolate, classify, ...) to generalize and predict from training examples; estimation of parameters is only an intermediate step
- nonpredictive features in any signal are useless since we observe now and react in the future
- high predictability sources (more details to predict, not easier predictions)
 are generated by more complex sources (in particular, regular and random
 sources have low complexity)

- we learn (estimate parameters, extrapolate, classify, ...) to generalize and predict from training examples; estimation of parameters is only an intermediate step
- nonpredictive features in any signal are useless since we observe now and react in the future
- high predictability sources (more details to predict, not easier predictions)
 are generated by more complex sources (in particular, regular and random
 sources have low complexity)
- measuring organisms' learning and prediction performance for signals of different complexity may reveal the underlying models

- we learn (estimate parameters, extrapolate, classify, ...) to generalize and predict from training examples; estimation of parameters is only an intermediate step
- nonpredictive features in any signal are useless since we observe now and react in the future
- high predictability sources (more details to predict, not easier predictions)
 are generated by more complex sources (in particular, regular and random
 sources have low complexity)
- measuring organisms' learning and prediction performance for signals of different complexity may reveal the underlying models
- optimizing predictive information may be the design principle

Information theory: non-metric, universal way to quantify learning



Information theory: non-metric, universal way to quantify learning

$$\mathcal{I}_{\text{pred}}(T, T') = \left\langle \log_2 \left[\frac{P(x_{\text{future}} | x_{\text{past}})}{P(x_{\text{future}})} \right] \right\rangle$$
$$= S(T) + S(T') - S(T + T')$$

Information theory: non-metric, universal way to quantify learning

$$\mathcal{I}_{\text{pred}}(T, T') = \left\langle \log_2 \left[\frac{P(x_{\text{future}} | x_{\text{past}})}{P(x_{\text{future}})} \right] \right\rangle$$

$$= S(T) + S(T') - S(T + T')$$

$$S(T) = S_0 \cdot T + S_1(T)$$

Extensive component cancels in predictive information.

Predictability is a deviation from extensivity!

Information theory: non-metric, universal way to quantify learning

$$\mathcal{I}_{\text{pred}}(T, T') = \left\langle \log_2 \left[\frac{P(x_{\text{future}} | x_{\text{past}})}{P(x_{\text{future}})} \right] \right\rangle$$
$$= S(T) + S(T') - S(T + T')$$
$$S(T) = S_0 \cdot T + S_1(T)$$

Extensive component cancels in predictive information.

Predictability is a deviation from extensivity!

$$I_{\text{pred}}(T) \equiv \mathcal{I}_{\text{pred}}(T, \infty) = S_1(T)$$

ullet $I_{\mathrm{pred}}(T)$ is information, so $I_{\mathrm{pred}}(T) \geq 0$

- $I_{\mathrm{pred}}(T)$ is information, so $I_{\mathrm{pred}}(T) \geq 0$
- $I_{\mathrm{pred}}(T)$ is subextensive, $\lim_{T \to \infty} \frac{I_{\mathrm{pred}}(T)}{T} = 0$

- $I_{\mathrm{pred}}(T)$ is information, so $I_{\mathrm{pred}}(T) \geq 0$
- $I_{\mathrm{pred}}(T)$ is subextensive, $\lim_{T\to\infty}\frac{I_{\mathrm{pred}}(T)}{T}=0$
- diminishing returns, $\lim_{T \to \infty} \frac{I_{\mathrm{pred}}(T)}{S(T)} = 0$

- $I_{\mathrm{pred}}(T)$ is information, so $I_{\mathrm{pred}}(T) \geq 0$
- $I_{\mathrm{pred}}(T)$ is subextensive, $\lim_{T\to\infty}\frac{I_{\mathrm{pred}}(T)}{T}=0$
- diminishing returns, $\lim_{T \to \infty} \frac{I_{\mathrm{pred}}(T)}{S(T)} = 0$
- prediction and postdiction are symmetric

- $I_{\mathrm{pred}}(T)$ is information, so $I_{\mathrm{pred}}(T) \geq 0$
- $I_{\mathrm{pred}}(T)$ is subextensive, $\lim_{T\to\infty}\frac{I_{\mathrm{pred}}(T)}{T}=0$
- diminishing returns, $\lim_{T\to\infty} \frac{I_{\mathrm{pred}}(T)}{S(T)} = 0$
- prediction and postdiction are symmetric
- it relates to and generalizes many relevant quantities
 - learning: universal learning curves
 - complexity: complexity measures
 - coding: model coding length

How can I_{pred} behave?

 $\lim_{N o \infty} I_{\mathrm{pred}} = \mathrm{const}$ no long-range structure

- simply predictable (periodic, constant, etc.) processes
- fully stochastic (Markov) processes

How can I_{pred} behave?

 $\lim_{N\to\infty}I_{\mathrm{pred}}=\mathrm{const}$ no long-range structure

- simply predictable (periodic, constant, etc.) processes
- fully stochastic (Markov) processes

 $\lim_{N \to \infty} I_{\mathrm{pred}} = \mathrm{const} imes \log_2 N$ precise learning of a fixed set of parameters

- learning finite-parameter densities
- well known as $I(N, parameters) = I_{pred}(N)$
- physical system at criticality
- (possibly) nonextensive statistics systems

How can I_{pred} behave?

 $\lim_{N\to\infty}I_{\mathrm{pred}}=\mathrm{const}$ no long-range structure

- simply predictable (periodic, constant, etc.) processes
- fully stochastic (Markov) processes

 $\lim_{N \to \infty} I_{\mathrm{pred}} = \mathrm{const} imes \log_2 N$ precise learning of a fixed set of parameters

- learning finite-parameter densities
- well known as $I(N, parameters) = I_{pred}(N)$
- physical system at criticality
- (possibly) nonextensive statistics systems

 $\lim_{N \to \infty} I_{\mathrm{pred}} = \mathrm{const} \times N^{\xi}$ learning more features as N grows

- learning continuous densities
- language
- some critical phenomena (wetting transitions)
- not well studied

Which complexity do we want to define?

- complexity of dynamics that generates a time series (not computational or descriptive complexity); thus it must be zero for totally random and for easily predictable processes
- usable for Occam—style punishment in statistical inference
- expressible in conventional physical terms
- must be attached to an ensemble, not a single realization

Complexity measure

• some kind of entropy (we proclaim Shannon's postulates: monotonicity, continuity, additivity)

Complexity measure

- some kind of entropy (we proclaim Shannon's postulates: monotonicity, continuity, additivity)
- invariant under invertible temporally local transformations $(x_k \rightarrow x_k + \xi x_{k-1})$: measuring device with inertia, article with misprints, same book in different languages same universality class)

$$\log P_1(x) = \log P_2(x) + \text{loc. oper.} \implies C[P_1(x)] = C[P_2(x)]$$

This may present a problem in higher dimensions.

Complexity measure

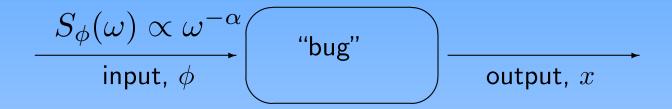
- some kind of entropy (we proclaim Shannon's postulates: monotonicity, continuity, additivity)
- invariant under invertible temporally local transformations $(x_k \rightarrow x_k + \xi x_{k-1})$: measuring device with inertia, article with misprints, same book in different languages same universality class)

$$\log P_1(x) = \log P_2(x) + \text{loc. oper.} \implies C[P_1(x)] = C[P_2(x)]$$

This may present a problem in higher dimensions.

The divergent subextensive term measures complexity uniquely!

$I_{ m pred}$ optimization in biology



$I_{ m pred}$ optimization in biology

$$\tau \frac{dx}{dt} = -x + \phi(t) + \eta(t), \quad \langle \eta(t)\eta(0) \rangle = 1/I_0 \,\delta(t)$$

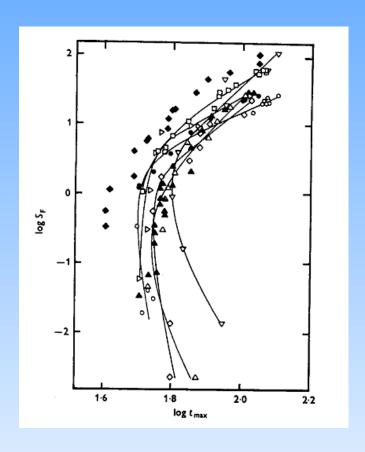
$I_{ m pred}$ optimization in biology

$$\tau \frac{dx}{dt} = -x + \phi(t) + \eta(t), \quad \langle \eta(t)\eta(0) \rangle = 1/I_0 \,\delta(t)$$

$$\mathcal{I}([\phi], [x]) = \lim_{T \to \infty} \frac{1}{2T} \int_{-T/2}^{T/2} \frac{d\omega}{2\pi} \log\left(1 + \frac{S_{\phi}(\omega)}{1/I_0}\right)$$

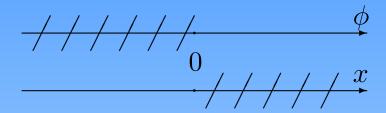
Maximization w.r.t. τ is meaningless.

$I_{ m pred}$ extraction and maximization

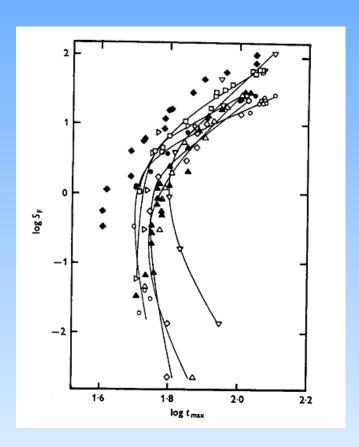


(Baylor and Hodgkin, 1974)

$I_{ m pred}$ extraction and maximization

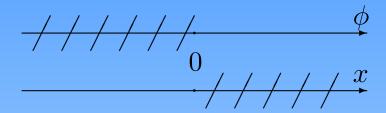


 $I([x_{\mathrm{past}}], [\phi_{\mathrm{future}}])$ – too difficult



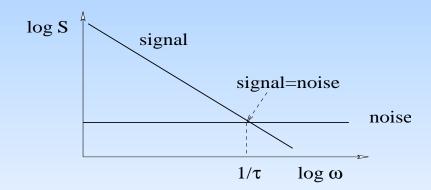
(Baylor and Hodgkin, 1974)

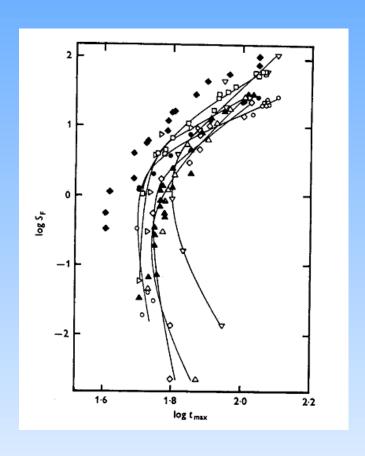
$I_{ m pred}$ extraction and maximization



 $I([x_{\mathrm{past}}], [\phi_{\mathrm{future}}])$ – too difficult

$$I(x_0, \phi_0) = \log \frac{\langle \phi^2 \rangle}{\langle \phi^2 \rangle - \frac{\langle \phi_f^2 \rangle^2}{\langle x^2 \rangle}}$$





(Baylor and Hodgkin, 1974)

Specific examples: problem setup

 $Q(\vec{x}|\alpha)$ p. d. f. for \vec{x} parameterized by unknown parameters α $\dim \alpha = K$ dimensionality of α , may be infinite $\mathcal{P}(\alpha)$ prior distribution of parameters $\vec{x}_1 \cdots \vec{x}_N$ random samples from the distribution

Specific examples: problem setup

 $Q(\vec{x}|\alpha)$ p. d. f. for \vec{x} parameterized by unknown parameters α $\dim \alpha = K$ dimensionality of α , may be infinite $\mathcal{P}(\alpha)$ prior distribution of parameters $\vec{x}_1 \cdots \vec{x}_N$ random samples from the distribution

$$P(\vec{x}_1, \vec{x}_2, \dots, \vec{x}_N | \boldsymbol{\alpha}) = \prod_{i=1}^{N} Q(\vec{x}_i | \boldsymbol{\alpha})$$

$$P(\vec{x}_1, \vec{x}_2, \dots, \vec{x}_N) = \int d^K \alpha \mathcal{P}(\boldsymbol{\alpha}) \prod_{i=1}^{N} Q(\vec{x}_i | \boldsymbol{\alpha})$$

$$S(\vec{x}_1, \vec{x}_2, \dots, \vec{x}_N) \equiv S(N)$$

$$= -\int d\vec{x}_1 \dots d\vec{x}_N P(\{\vec{x}_i\}) \log_2 P(\{\vec{x}_i\})$$

Separating the terms

$$S_{0} = \int d^{K} \alpha \mathcal{P}(\boldsymbol{\alpha}) \left[-\int d\vec{x} Q(\vec{x}|\boldsymbol{\alpha}) \log_{2} Q(\vec{x}|\boldsymbol{\alpha}) \right]$$

$$S_{1}(N) = -\int d^{K} \bar{\alpha} d^{N} \vec{x_{i}} \mathcal{P}(\bar{\boldsymbol{\alpha}}) \prod Q(\vec{x_{i}}|\bar{\boldsymbol{\alpha}}) \log_{2} \int d^{K} \alpha \mathcal{P}(\boldsymbol{\alpha}) e^{-N\mathcal{E}_{N}}$$

Separating the terms

$$S_{0} = \int d^{K} \alpha \mathcal{P}(\boldsymbol{\alpha}) \left[- \int d\vec{x} Q(\vec{x}|\boldsymbol{\alpha}) \log_{2} Q(\vec{x}|\boldsymbol{\alpha}) \right]$$

$$S_{1}(N) = - \int d^{K} \bar{\alpha} d^{N} \vec{x_{i}} \mathcal{P}(\bar{\boldsymbol{\alpha}}) \prod Q(\vec{x_{i}}|\bar{\boldsymbol{\alpha}}) \log_{2} \int d^{K} \alpha \mathcal{P}(\boldsymbol{\alpha}) e^{-N\mathcal{E}_{N}}$$

$$\mathcal{E}_{N} \equiv \frac{1}{N} \sum_{i} \log \left[\frac{Q(\vec{x}_{i} | \bar{\boldsymbol{\alpha}})}{Q(\vec{x}_{i} | \boldsymbol{\alpha})} \right] \xrightarrow{\text{anneal}} \int d\vec{x} \, Q(\vec{x} | \bar{\boldsymbol{\alpha}}) \log \frac{Q(\vec{x} | \bar{\boldsymbol{\alpha}})}{Q(\vec{x} | \boldsymbol{\alpha})}$$

Annealed approximation (almost) always works.

Density of states

$$Z(\bar{\alpha}; N) = \int d\epsilon \, \rho(\epsilon; \bar{\alpha}) \exp[-N\epsilon]$$

$$\rho(\epsilon; \bar{\alpha}) = \int d^K \alpha \, \mathcal{P}(\alpha) \delta[\epsilon - D_{\mathrm{KL}}(\bar{\alpha}||\alpha)]$$

Density of states

$$Z(\bar{\boldsymbol{\alpha}};N) = \int d\epsilon \, \rho(\epsilon;\bar{\boldsymbol{\alpha}}) \exp[-N\epsilon]$$

$$\rho(\epsilon;\bar{\boldsymbol{\alpha}}) = \int d^K \alpha \, \mathcal{P}(\boldsymbol{\alpha}) \delta[\epsilon - D_{\mathrm{KL}}(\bar{\boldsymbol{\alpha}}||\boldsymbol{\alpha})]$$

$$\int d\epsilon \, \rho(\epsilon;\bar{\boldsymbol{\alpha}}) = \int d^K \alpha \, \mathcal{P}(\boldsymbol{\alpha}) = 1 \quad \text{annealing works!}$$

Density of states

$$Z(\bar{\boldsymbol{\alpha}};N) = \int d\epsilon \, \rho(\epsilon;\bar{\boldsymbol{\alpha}}) \exp[-N\epsilon]$$

$$\rho(\epsilon;\bar{\boldsymbol{\alpha}}) = \int d^K \alpha \, \mathcal{P}(\boldsymbol{\alpha}) \delta[\epsilon - D_{\mathrm{KL}}(\bar{\boldsymbol{\alpha}}||\boldsymbol{\alpha})]$$

$$\int d\epsilon \, \rho(\epsilon;\bar{\boldsymbol{\alpha}}) = \int d^K \alpha \, \mathcal{P}(\boldsymbol{\alpha}) = 1 \quad \text{annealing works!}$$

Learning is annealing at decreasing temperature. Nonzero $\rho \Longrightarrow$ consistency in learning.

Density at $\epsilon \to 0$, I_{pred} , and learning

Occam factor, generalization error, prediction error, fluctuation determinant:

$$\mathcal{D}(\bar{\boldsymbol{\alpha}}; N) \approx -\log \int d\epsilon \, \rho(\epsilon; \bar{\boldsymbol{\alpha}}) e^{-N\epsilon}$$

Density at $\epsilon \to 0$, I_{pred} , and learning

Occam factor, generalization error, prediction error, fluctuation determinant:

$$\mathcal{D}(\bar{\boldsymbol{\alpha}}; N) \approx -\log \int d\epsilon \, \rho(\epsilon; \bar{\boldsymbol{\alpha}}) e^{-N\epsilon}$$

Predictive information:

$$I_{\mathrm{pred}}(N) pprox \int d^K \bar{\alpha} \, \mathcal{P}(\bar{\boldsymbol{\alpha}}) \, \mathcal{D}(\bar{\boldsymbol{\alpha}}, N)$$

Density at $\epsilon \to 0$, I_{pred} , and learning

Occam factor, generalization error, prediction error, fluctuation determinant:

$$\mathcal{D}(\bar{\boldsymbol{\alpha}}; N) \approx -\log \int d\epsilon \, \rho(\epsilon; \bar{\boldsymbol{\alpha}}) e^{-N\epsilon}$$

Predictive information:

$$I_{\mathrm{pred}}(N) pprox \int d^K \bar{\alpha} \, \mathcal{P}(\bar{\boldsymbol{\alpha}}) \, \mathcal{D}(\bar{\boldsymbol{\alpha}}, N)$$

Universal learning curves:

$$\Lambda(\bar{\boldsymbol{\alpha}}; N) \equiv D_{\mathrm{KL}}(\bar{\boldsymbol{\alpha}}||\boldsymbol{\alpha}_{\mathrm{est}}) \approx \frac{d\mathcal{D}(\bar{\boldsymbol{\alpha}}; N)}{dN}$$
$$\Lambda(N) \equiv \int d\bar{\boldsymbol{\alpha}} \, \mathcal{P}(\bar{\boldsymbol{\alpha}}) \Lambda(\bar{\boldsymbol{\alpha}}; N) \approx \frac{dI_{\mathrm{pred}}}{dN}$$

Finite number of states and finite I_{pred}

$$\rho(\epsilon; a_i) = \sum_{j=1}^{M} \mathcal{P}_j \, \delta(d_{ij} - \epsilon)$$

Finite number of states and finite $I_{ m pred}$

$$\rho(\epsilon; a_i) = \sum_{j=1}^{M} \mathcal{P}_j \, \delta(d_{ij} - \epsilon)$$

$$\mathcal{D}(a_i; N) = c_1 - c_2 \, \exp[-Nc_3]$$

$$\Lambda(a_i; N) \approx c_2 c_3 \exp[-Nc_3]$$

 I_{pred} saturates as $N \to \infty$

Power-law density function

$$\rho(\epsilon \to 0; \bar{\alpha}) \approx A(\bar{\alpha}) \epsilon^{(d-2)/2}$$

Power-law density function

$$\rho(\epsilon \to 0; \bar{\alpha}) \approx A(\bar{\alpha}) \epsilon^{(d-2)/2}$$

Example: sound finite parameter models, $\dim \alpha = d$.

$$\rho(\epsilon; \bar{\boldsymbol{\alpha}}) \stackrel{\epsilon \to 0}{\longrightarrow} \mathcal{P}(\bar{\boldsymbol{\alpha}}) \frac{2\pi^{d/2}}{\Gamma(d/2)} (\det \mathcal{F})^{-1/2} \epsilon^{(d-2)/2}$$

$$I_{\text{pred}} \approx S_1^{(a)} \approx \frac{d}{2} \log_2 N$$

Power-law density function

$$\rho(\epsilon \to 0; \bar{\alpha}) \approx A(\bar{\alpha}) \epsilon^{(d-2)/2}$$

Example: sound finite parameter models, $\dim \alpha = d$.

$$\rho(\epsilon; \bar{\boldsymbol{\alpha}}) \stackrel{\epsilon \to 0}{\longrightarrow} \mathcal{P}(\bar{\boldsymbol{\alpha}}) \frac{2\pi^{d/2}}{\Gamma(d/2)} (\det \mathcal{F})^{-1/2} \epsilon^{(d-2)/2}$$

$$I_{\text{pred}} \approx S_1^{(a)} \approx \frac{d}{2} \log_2 N$$

Speed of approach to this asymptotics is rarely investigated.

Another example

Learning $Q(\vec{x}_1 \cdots \vec{x}_N | \alpha)$, a finite parameter Markov process with long range intrinsic correlations such that

$$S\left[\{\vec{x}_i\}|\boldsymbol{\alpha}\right] \equiv -\int d^N \vec{x} \, Q(\{\vec{x}_i\}|\boldsymbol{\alpha}) \, \log_2 Q(\{\vec{x}_i\}|\boldsymbol{\alpha})$$

$$\rightarrow N\mathcal{S}_0 + \mathcal{S}_0^*; \qquad \mathcal{S}_0^* = \frac{K'}{2} \log_2 N$$

Another example

Learning $Q(\vec{x}_1 \cdots \vec{x}_N | \alpha)$, a finite parameter Markov process with long range intrinsic correlations such that

$$S\left[\{\vec{x}_i\}|\boldsymbol{\alpha}\right] \equiv -\int d^N \vec{x} \, Q(\{\vec{x}_i\}|\boldsymbol{\alpha}) \, \log_2 Q(\{\vec{x}_i\}|\boldsymbol{\alpha})$$

$$\rightarrow N\mathcal{S}_0 + \mathcal{S}_0^*; \qquad \mathcal{S}_0^* = \frac{K'}{2} \log_2 N$$

$$S_1^{(a)}(N) \approx \frac{K + K'}{2} \log_2 N$$

Another example

Learning $Q(\vec{x}_1 \cdots \vec{x}_N | \alpha)$, a finite parameter Markov process with long range intrinsic correlations such that

$$S\left[\{\vec{x}_i\}|\boldsymbol{\alpha}\right] \equiv -\int d^N \vec{x} \, Q(\{\vec{x}_i\}|\boldsymbol{\alpha}) \, \log_2 Q(\{\vec{x}_i\}|\boldsymbol{\alpha})$$

$$\rightarrow NS_0 + S_0^*; \qquad S_0^* = \frac{K'}{2} \log_2 N$$

$$S_1^{(a)}(N) \approx \frac{K + K'}{2} \log_2 N$$

Do not distinguish predictability from unknown parameters and from intrinsic correlations.

In physics similar to: order parameters \iff interactions.

Essential singularity in the density

$$\rho(\epsilon \to 0; \bar{\alpha}) \approx A(\bar{\alpha}) \exp\left[-\frac{B(\bar{\alpha})}{\epsilon^{\mu}}\right], \quad \mu > 0$$

$$S_1^{(a)}(N) \propto N^{\mu/(\mu+1)}$$

Essential singularity in the density

$$ho(\epsilon \to 0; \bar{\alpha}) \approx A(\bar{\alpha}) \exp\left[-\frac{B(\bar{\alpha})}{\epsilon^{\mu}}\right], \quad \mu > 0$$

$$S_1^{(a)}(N) \propto N^{\mu/(\mu+1)}$$

- finite parameter model with increasing number of parameters $K \sim N^{\mu/(\mu+1)}$; $S_1(N) \sim N^{\mu/\mu+1}$, not $S_1(N) \sim \frac{N^{\mu/\mu+1}}{2} \log N$
- as $\mu \to \infty$ complexity grows and then vanishes to the leading order when $S_1^{({\rm a})}$ becomes extensive

Example of the power–law $I_{ m pred}$

Learning a smooth nonparameteric density $Q(x) = 1/l_0 \mathrm{e}^{-\phi(x)}$, $x \in [0, L]$ (Bialek, Callan, and Strong 1996), Complete model.

$$\mathcal{P}[\phi(x)] = \frac{1}{\mathcal{Z}} \exp\left[-\frac{l}{2} \int dx \left(\frac{\partial \phi}{\partial x}\right)^2\right] \delta\left[\frac{1}{l_0} \int dx \, e^{-\phi(x)} - 1\right]$$

Example of the power–law I_{pred}

Learning a smooth nonparameteric density $Q(x)=1/l_0\mathrm{e}^{-\phi(x)}$, $x\in[0,L]$ (Bialek, Callan, and Strong 1996), Complete model.

$$\mathcal{P}[\phi(x)] = \frac{1}{\mathcal{Z}} \exp\left[-\frac{l}{2} \int dx \left(\frac{\partial \phi}{\partial x}\right)^2\right] \delta\left[\frac{1}{l_0} \int dx \, \mathrm{e}^{-\phi(x)} - 1\right]$$

$$\rho(D \to 0; \bar{\phi}) = A[\bar{\phi}(x)] \epsilon^{-3/2} \exp\left(-\frac{B[\bar{\phi}(x)]}{\epsilon}\right)$$

$$S_1^{(\mathrm{a})}(N) \propto \sqrt{N} \left(\frac{L}{l}\right)^{1/2}$$

Example of the power–law $I_{ m pred}$

Learning a smooth nonparameteric density $Q(x)=1/l_0\mathrm{e}^{-\phi(x)}$, $x\in[0,L]$ (Bialek, Callan, and Strong 1996), Complete model.

$$\mathcal{P}[\phi(x)] = \frac{1}{\mathcal{Z}} \exp\left[-\frac{l}{2} \int dx \left(\frac{\partial \phi}{\partial x}\right)^2\right] \delta\left[\frac{1}{l_0} \int dx \, \mathrm{e}^{-\phi(x)} - 1\right]$$

$$\rho(D \to 0; \bar{\phi}) = A[\bar{\phi}(x)] \epsilon^{-3/2} \exp\left(-\frac{B[\bar{\phi}(x)]}{\epsilon}\right)$$

$$S_1^{(\mathrm{a})}(N) \propto \sqrt{N} \left(\frac{L}{l}\right)^{1/2}$$

• increasing number of "effective parameters" (bins) of adaptive size $\sim \sqrt{l/NQ(x)}$

Example of the power–law $I_{ m pred}$

Learning a smooth nonparameteric density $Q(x)=1/l_0\mathrm{e}^{-\phi(x)}$, $x\in[0,L]$ (Bialek, Callan, and Strong 1996), Complete model.

$$\mathcal{P}[\phi(x)] = \frac{1}{\mathcal{Z}} \exp\left[-\frac{l}{2} \int dx \left(\frac{\partial \phi}{\partial x}\right)^2\right] \delta\left[\frac{1}{l_0} \int dx \, \mathrm{e}^{-\phi(x)} - 1\right]$$

$$\rho(D \to 0; \bar{\phi}) = A[\bar{\phi}(x)] \epsilon^{-3/2} \exp\left(-\frac{B[\bar{\phi}(x)]}{\epsilon}\right)$$

$$S_1^{(\mathrm{a})}(N) \propto \sqrt{N} \left(\frac{L}{l}\right)^{1/2}$$

- ullet increasing number of "effective parameters" (bins) of adaptive size $\sim \sqrt{l/NQ(x)}$
- heuristic arguments for the dimensionality ζ and the smoothness exponent η give $S_1(N)\sim N^{\zeta/2\eta}$ demonstrates a crossover from complexity to randomness

Nested finite parameter models, $r = 1 \dots \infty$, K = K(r), $\mathcal{P}(r)$:

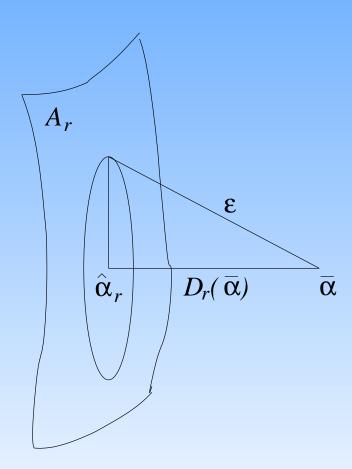
$$\mathcal{P}(\alpha_{\mu}|r) = \begin{cases} p(\alpha_{\mu}), & \mu \leq K(r) \\ \delta(\alpha_{\mu}), & \mu > K(r) \end{cases}$$

$$\mathcal{P}(\boldsymbol{\alpha}|r) = \prod_{\mu=1}^{R} \mathcal{P}(\alpha_{\mu}|r)$$

Nested finite parameter models, $r = 1 \dots \infty$, K = K(r), $\mathcal{P}(r)$:

$$\mathcal{P}(\alpha_{\mu}|r) = \begin{cases} p(\alpha_{\mu}), & \mu \leq K(r) \\ \delta(\alpha_{\mu}), & \mu > K(r) \end{cases}$$

$$\mathcal{P}(\boldsymbol{\alpha}|r) = \prod_{\mu=1}^{R} \mathcal{P}(\alpha_{\mu}|r)$$



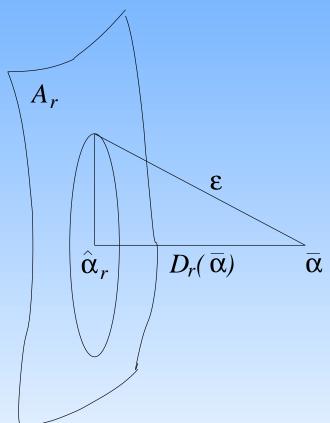
Nested finite parameter models, $r = 1 \dots \infty$, K = K(r), $\mathcal{P}(r)$:

$$\mathcal{P}(\alpha_{\mu}|r) = \begin{cases} p(\alpha_{\mu}), & \mu \leq K(r) \\ \delta(\alpha_{\mu}), & \mu > K(r) \end{cases}$$

$$\mathcal{P}(\boldsymbol{\alpha}|r) = \prod_{\mu=1}^{R} \mathcal{P}(\alpha_{\mu}|r)$$

$$\rho(\epsilon; \bar{\boldsymbol{\alpha}}) = \sum_{r: D_{r}(\bar{\boldsymbol{\alpha}}) \leq \epsilon} \mathcal{P}(r) \mathcal{P}(\hat{\boldsymbol{\alpha}}_{r}|r)$$

$$\frac{2\pi^{K(r)/2}}{\Gamma[K(r)/2]} \frac{[\epsilon^{2} - D_{r}^{2}(\bar{\boldsymbol{\alpha}})]^{[K(r)-2]/4}}{\sqrt{\det \mathcal{F}_{K(r)}}}$$



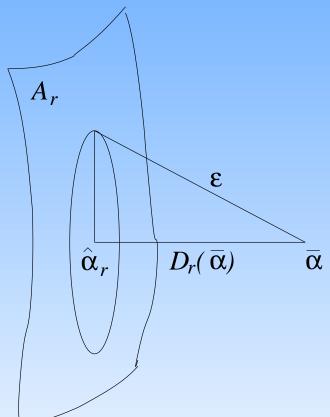
Nested finite parameter models, $r=1\ldots\infty$, K=K(r), $\mathcal{P}(r)$:

$$\mathcal{P}(\alpha_{\mu}|r) = \begin{cases} p(\alpha_{\mu}), & \mu \leq K(r) \\ \delta(\alpha_{\mu}), & \mu > K(r) \end{cases}$$

$$\mathcal{P}(\boldsymbol{\alpha}|r) = \prod_{\mu=1}^{R} \mathcal{P}(\alpha_{\mu}|r)$$

$$\rho(\epsilon; \bar{\boldsymbol{\alpha}}) = \sum_{r: D_{r}(\bar{\boldsymbol{\alpha}}) \leq \epsilon} \mathcal{P}(r) \mathcal{P}(\hat{\boldsymbol{\alpha}}_{r}|r)$$

$$\frac{2\pi^{K(r)/2}}{\Gamma[K(r)/2]} \frac{[\epsilon^{2} - D_{r}^{2}(\bar{\boldsymbol{\alpha}})]^{[K(r)-2]/4}}{\sqrt{\det \mathcal{F}_{K(r)}}}$$



Another complete model!

$$ho(\epsilon; ar{m{lpha}}) \sim \epsilon^{\epsilon^{-1/(2\eta-1)}\ell^{-1}}$$
 $ho(\epsilon; ar{m{lpha}}) \propto N^{1/2\eta} \left(\frac{\log N}{\ell}\right)^{1-1/2\eta}$

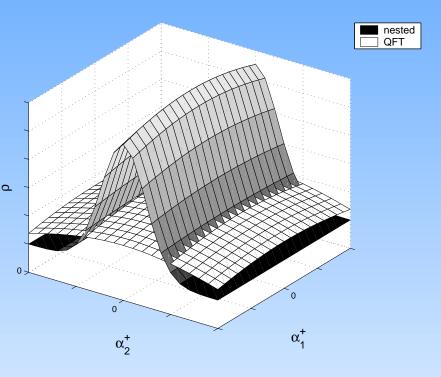
$$ho(\epsilon; \bar{\boldsymbol{\alpha}}) \sim \epsilon^{\epsilon^{-1/(2\eta-1)}\ell^{-1}}$$
 $\mathcal{D} \propto N^{1/2\eta} \left(\frac{\log N}{\ell}\right)^{1-1/2\eta}$

- nested model is at most log worse than the QFT
- QFT may be a power law worse

$$\rho(\epsilon; \bar{\boldsymbol{\alpha}}) \sim \epsilon^{\epsilon^{-1/(2\eta-1)}\ell^{-1}}$$

$$ho(\epsilon; \bar{\boldsymbol{\alpha}}) \sim \epsilon^{\epsilon^{-1/(2\eta-1)}\ell^{-1}}$$
 $\mathcal{D} \propto N^{1/2\eta} \left(\frac{\log N}{\ell}\right)^{1-1/2\eta}$

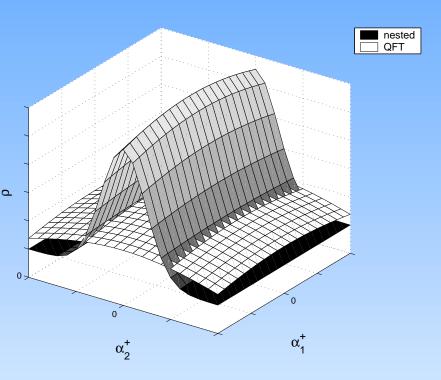
- nested model is at most log worse than the QFT
- QFT may be a power law worse



$$\rho(\epsilon; \bar{\boldsymbol{\alpha}}) \sim \epsilon^{\epsilon^{-1/(2\eta-1)}\ell^{-1}}$$

$$ho(\epsilon; \bar{\boldsymbol{\alpha}}) \sim \epsilon^{\epsilon^{-1/(2\eta-1)}\ell^{-1}}$$
 $\mathcal{D} \propto N^{1/2\eta} \left(\frac{\log N}{\ell}\right)^{1-1/2\eta}$

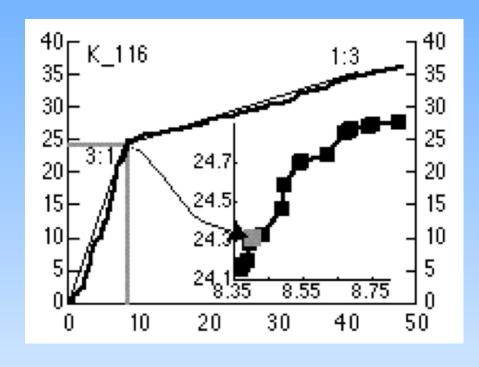
- nested model is at most log worse than the QFT
- QFT may be a power law worse
- for natural (structured) data nested case is better
- alignment may be imperfect for finite precision ϵ



Which model is being used?

- for QFT or nested asymptotics kicks in fast
- asymptotic decay rate should signify the model

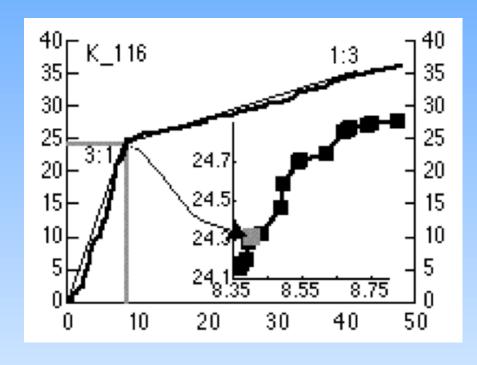
Which model is being used?



- for QFT or nested asymptotics kicks in fast
- asymptotic decay rate should signify the model
- decay rate too fast to observe
- noisy learning

(Gallistel et al., 2001)

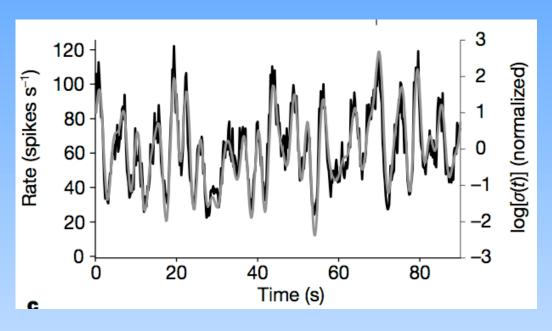
Which model is being used?



- for QFT or nested asymptotics kicks in fast
- asymptotic decay rate should signify the model
- decay rate too fast to observe
- noisy learning
- maybe FDT? $\frac{\partial \Lambda}{\partial N} = -\zeta_N \Lambda^{\nu}$

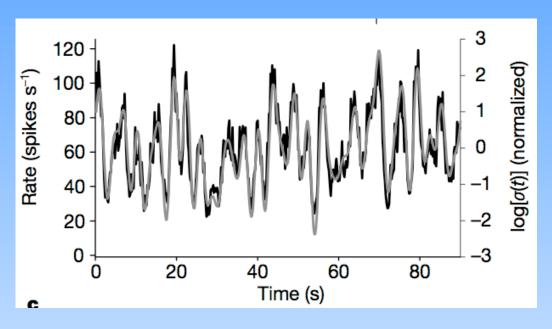
(Gallistel et al., 2001)

Fluctuations (drifting target) and dissipation (learning curve)



(Fairhall et al., 2001)

Fluctuations (drifting target) and dissipation (learning curve)



(Fairhall et al., 2001)

$$\Delta_{\rm rms} = \left\{ \nu^{1/\nu} \frac{\Gamma\left(\frac{3}{2\nu}\right)}{\Gamma\left(\frac{1}{2\nu}\right)} \right\}^{1/2} \left(\frac{\Omega}{\zeta}\right)^{1/(2\nu)}$$

The hidden extras. . .

... are mostly straightforward.

... are mostly straightforward.

For Kolmogorov complexity:

... are mostly straightforward.

For Kolmogorov complexity:

partition all strings into equivalence classes

... are mostly straightforward.

For Kolmogorov complexity:

- partition all strings into equivalence classes
- define Kolmogorov complexity $C_K(s)$ of a sequence s with respect to the partition as a length of the shortest program that can generate a sequence from the class s belongs to

... are mostly straightforward.

For Kolmogorov complexity:

- partition all strings into equivalence classes
- define Kolmogorov complexity $C_K(s)$ of a sequence s with respect to the partition as a length of the shortest program that can generate a sequence from the class s belongs to
- equivalence = indistinguishable conditional distributions of futures

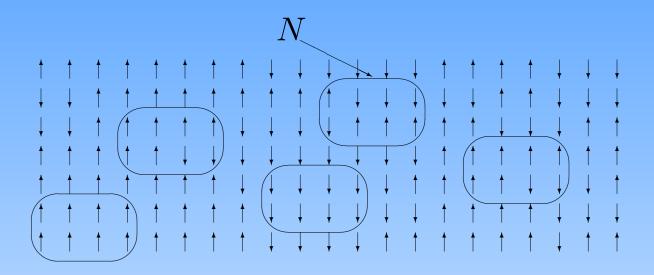
... are mostly straightforward.

For Kolmogorov complexity:

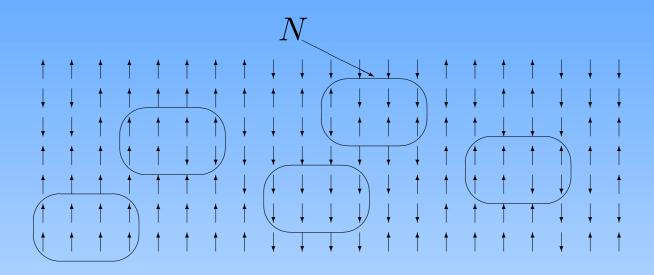
- partition all strings into equivalence classes
- define Kolmogorov complexity $C_K(s)$ of a sequence s with respect to the partition as a length of the shortest program that can generate a sequence from the class s belongs to
- equivalence = indistinguishable conditional distributions of futures

If sufficient statistics exist, then $C_K \approx I_{\text{pred}}$. Otherwise $C_K > I_{\text{pred}}$. C_K is unique up to a constant.

RG, not finite size scaling!



RG, not finite size scaling!



$$S(N) = S(block) + S(spin|block)$$

Scaling fields carry information across.

Is
$$I_{\text{pred}} = f(\text{scaling exponents}) \log N$$
?

What's next?

- **extraction** separating predictive information from non–predictive using the *Information Bottleneck* technique
- physics of phase transitions, connection to subextensive statistical mechanics
- **learning** unification of approaches: Bayesian, SRM, MDL, Cucker-Smale. . .
- bioinformatics what is predictive information of natural symbolic sequences (DNA, languages, spike trains)? animal behavior? can we use changes in predictability for data partitioning? for model building? dynamical systems theory what is predictive information and complexity of various systems?