Universal learning: a view of a Bayesian

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- 3. Which complexity?



$$P_{\text{est}}(\theta|\vec{x}) = \frac{P(\vec{x}|\theta)\mathcal{P}_{\text{est}}(\theta)}{P_{\text{est}}(\vec{x})}$$



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Universal learning \approx Bayesian learning with universal priors.

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- NFL: if you are ignorant and indicate this by *uniform prior*, then the best average performance is achieved by exhaustively searching over all functions.
- No such statements for *minimax* analysis.



 Bayesian model selection and universal learning start with well-defined, particular priors over functions, which is an assumption.

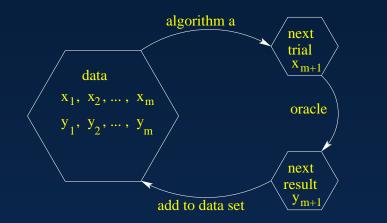
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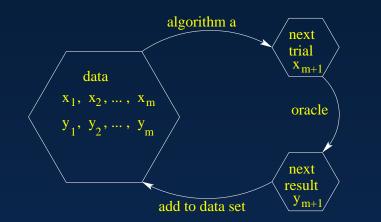
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- Probabilities are (roughly) uniform over sets of functions, and functions have nonuniform probabilities 1/||set||.
- For Bayesian model selection and for universal learning to win, on average, the world must be simple (an assumption).
- But you won't loose too much if it is not, and in this case you are doomed anyway.



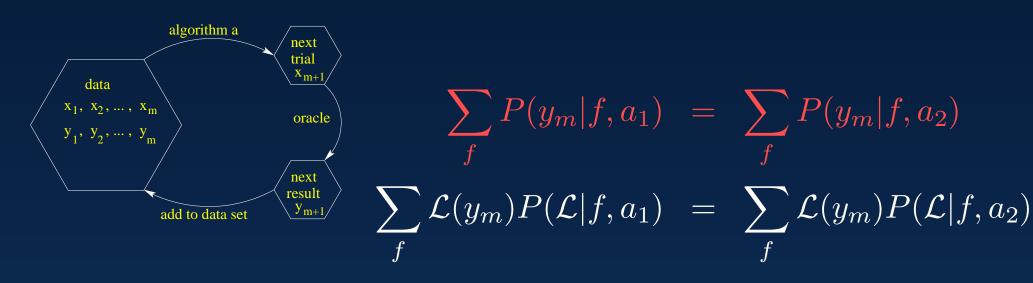




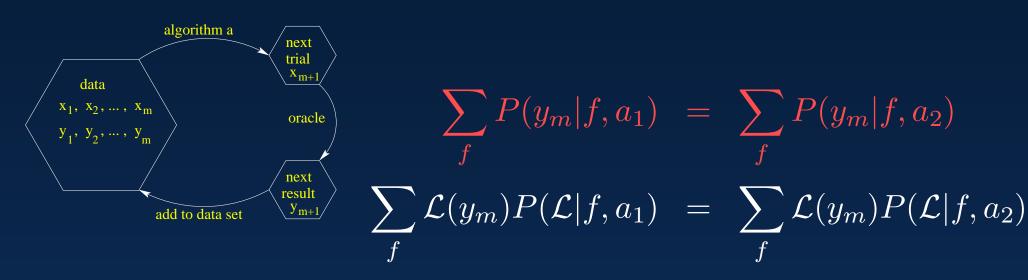


 $\sum_{f} P(y_m | f, a_1) = \sum_{f} P(y_m | f, a_2)$

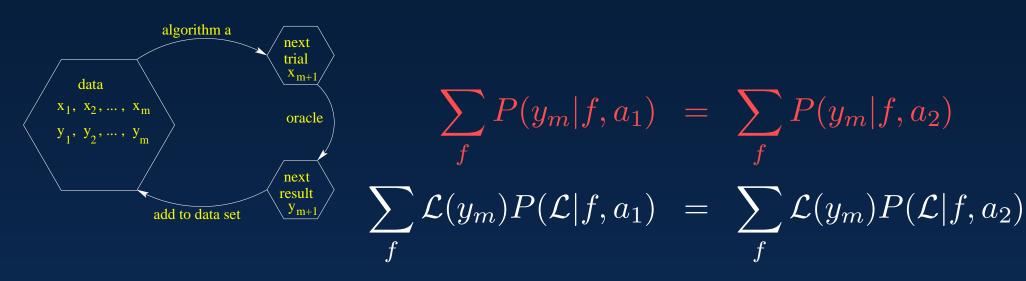




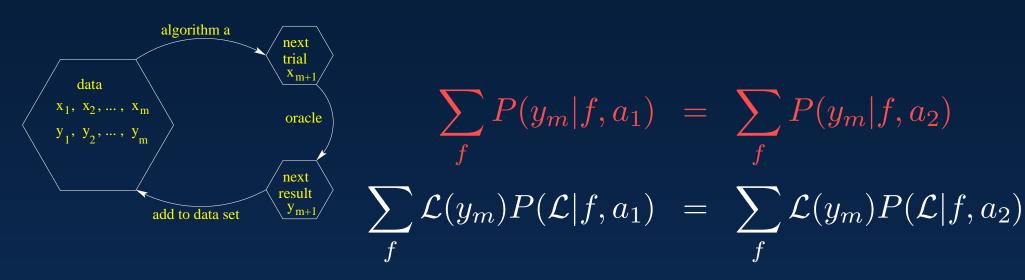




• Same holds for time-dependent optimization.

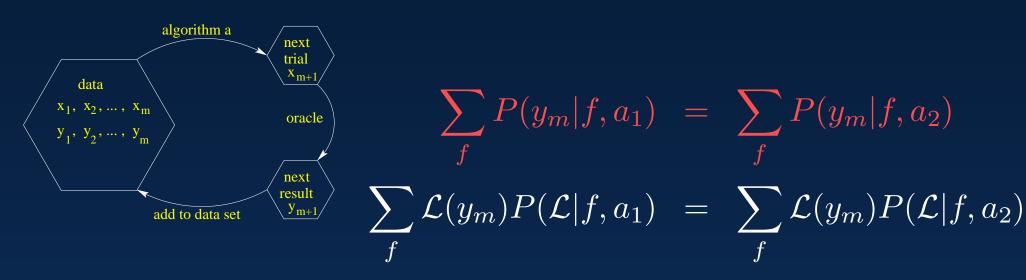


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For uniform prior over f, what is won on some f is lost on the others.



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Do not consider the interruption time, just the choice of the next guess.

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If the time till interrupt is also reweighted, things are more complicated.

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- For *average* performance matching of algorithms to priors is crucial.
- For *minimax* properties it is not crucial.
- Usually, one is interested in *average* performance for problems that are "good" and *minimax* performance on "bad" problems. NFL theorems do not say anything about universal/Occam priors in this case.



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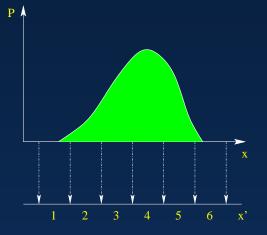
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- One has to quantize (discretize) it before supplying to a digital computer for analysis.
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- How does learning depend on a choice of coordinates and/or discretization?
- Are there performance bounds uniform over all parameterizations and/or discretizations?

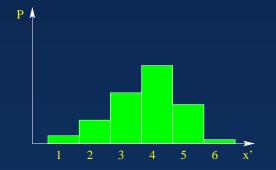


Uniform quantization



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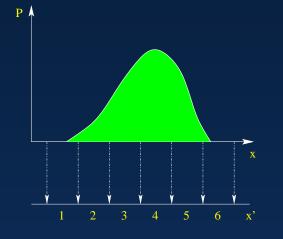






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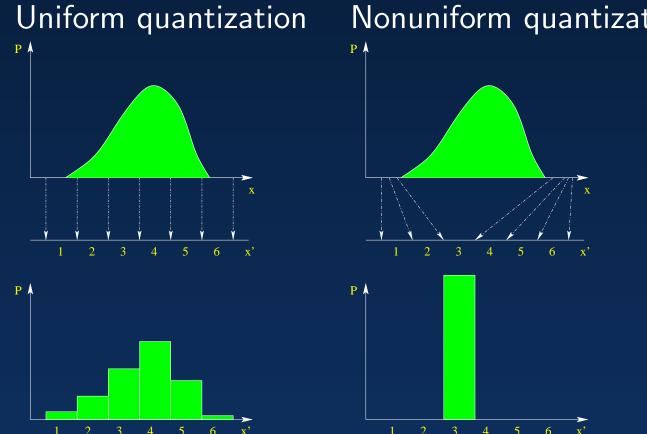
Nonuniform quantization





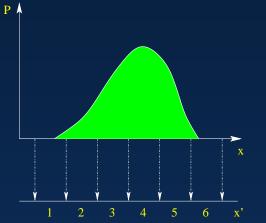


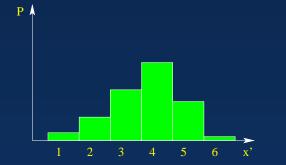
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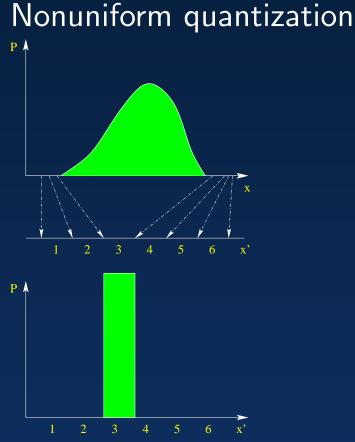




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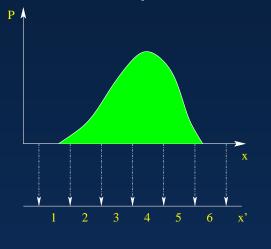




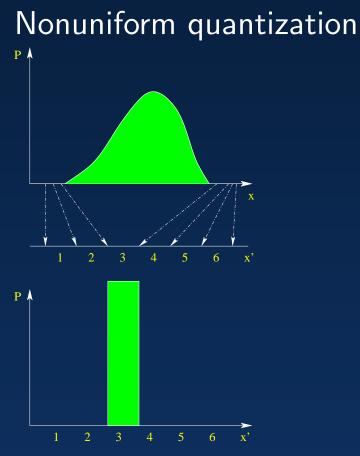
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Uniform quantization







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The question may be discretization dependent (e. g., finding the shortest path between two points).



Learning PDF's: covariance problem

There is a problem learning PDF's in a covariant way. Learning $(L : \{x_i\} \rightarrow P(x))$ and reparameterization $(R_z : x \rightarrow z(x))$ do not commute

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Similarly, quantization and learning do not commute.

Coordinate system $x \qquad z$			
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To overcome analogs of NFL theorems, we must assume that P has small K-complexity in the coordinate system we have chosen.

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Individual (Martin-Löf) randomness, typicalities, etc. still require (possibly implicit) ensemble specification (or Bernoulli ensemble is assumed – but why should one work with this *worst* case?)

Example

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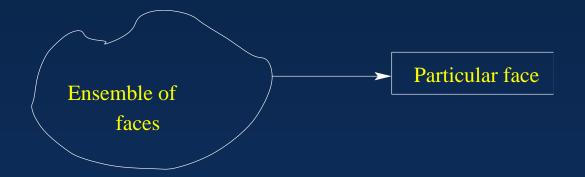




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For this ensemble the face is a random (typical) string.



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Complexity is an ensemble (averaged) quantity, even if the ensemble is only implicit.



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$$\begin{array}{cccc} T, N & 0 & T', N' & x \\ \hline past & now & future \\ \mathcal{I}_{pred}(T, T') &= \left\langle \log_2 \left[\frac{P(x_{future} | x_{past})}{P(x_{future})} \right] \right\rangle \\ &= S(T) + S(T') - S(T + T') \end{array}$$



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The divergent (in T or N) part of subextensive entropy term measures complexity uniquely!

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 $K_p(s)$ is basically the regular K(s) without the random part (i. e. zero description cost for using a random number generator.)

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